MAKING MODERN LIVING POSSIBLE

Programming Guide
VLT® Micro Drive FC 51

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VLT® THE REAL DRIVE

Contents

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1 Introduction

The nameplate sticker is located on the top of each frequency converter and shows the ratings, serial number, warnings catalog number, and other relevant data for each unit. See *Table 1.1* for details, how to read the type code string.

130BA505

Illustration 1.1 Nameplate Sticker

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1.1.1 Type Code

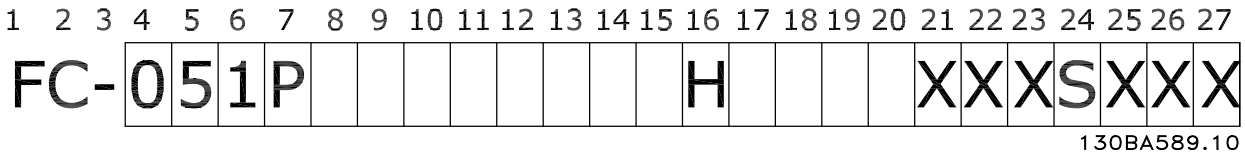


Illustration 1.2 Type Code Definition

Description	Pos.	Possible choice
Product group	1-3	Frequency converters
Series and product type	4-6	Micro Drive
Power size	7-10	0.18–22 kW
Mains voltage	11-12	S2: Single phase 200–240 V AC T2: 3-phase, 200–240 V AC T4: 3-phase, 380–480 V AC
Enclosure	13-15	IP20/Chassis
RFI filter	16-17	HX: No RFI filter H1: RFI filter class A1/B H3:RFI filter A1/B (reduced cable length[1)])
Brake	18	B: Brake chopper included (from 1.5 kW and up) X: No brake chopper included
Display	19	X: No Local Control Panel N: Numerical Local Control Panel (LCP) P: Numerical Local Control Panel (LCP)) with potentiometer
Coating PCB	20	C: Coated PCB X. No coated PCB
Mains option	21	X: No mains option
Adaptation A	22	X: No adaptation
Adaptation B	23	X: No adaptation
Software release	24-27	SXXX: Latest release - standard software

Table 1.1 Type Code Description

1) See the VLT® Micro Drive FC 51 Design Guide.

1.2 Abbreviations

Abbreviations	Terms	SI units	I-P units
a	Acceleration	m/s^2	ft/s^2
AWG	American wire gauge		
Auto Tune	Automatic motor tuning		
°C	Celsius		
I	Current	A	Amp
I_{LIM}	Current limit		
IT mains	Mains supply with star point in transformer floating to ground		
Joule	Energy	J=N·m	ft-lb, Btu
°F	Fahrenheit		
FC	Frequency converter		
f	Frequency	Hz	Hz
kHz	Kilohertz	kHz	kHz
LCP	Local control panel		
mA	Milliampere		
ms	Millisecond		
min	Minute		
MCT	Motion Control Tool		
M-TYPE	Motor type dependent		
Nm	Newton metres		in-lbs
$I_{M,N}$	Nominal motor current		
$f_{M,N}$	Nominal motor frequency		
$P_{M,N}$	Nominal motor power		
$U_{M,N}$	Nominal motor voltage		
PELV	Protective extra low voltage		
Watt	Power	W	Btu/hr, hp
Pascal	Pressure	Pa = N/m^2	psi, psf, ft of water
I_{INV}	Rated inverter output current		
RPM	Revolutions per minute		
s	Second		
SR	Size related		
T	Temperature	C	F
t	Time	s	s,hr
T_{LIM}	Torque limit		
U	Voltage	V	V

Table 1.2 Abbreviations

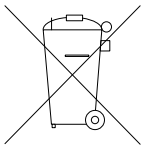
1.3 Software Version and Approvals

Software Version
Programming Guide
VLT® Micro Drive
FC 51 Series

This Programming Guide can be used for all VLT® Micro Drive FC 51 frequency converters with software version 3.1X.
The software version number can be read in *15-43 Software Version*.

Table 1.3 Software Version and Approvals

1.4 Disposal Instruction



Equipment containing electrical components must not be disposed of together with domestic waste.
It must be separately collected with electrical and electronic waste according to local and currently valid legislation.

2 Safety

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2.1 Safety Symbols

The following symbols are used in this manual:

⚠WARNING

Indicates a potentially hazardous situation that could result in death or serious injury.

⚠CAUTION

Indicates a potentially hazardous situation that could result in minor or moderate injury. It can also be used to alert against unsafe practices.

NOTICE

Indicates important information, including situations that can result in damage to equipment or property.

2.2 Qualified Personnel

Correct and reliable transport, storage, installation, operation, and maintenance are required for the trouble-free and safe operation of the frequency converter. Only qualified personnel are allowed to install or operate this equipment.

Qualified personnel are defined as trained staff, who are authorised to install, commission, and maintain equipment, systems, and circuits in accordance with pertinent laws and regulations. Additionally, the qualified personnel must be familiar with the instructions and safety measures described in these operating instructions.

2.3 Safety

⚠WARNING

HIGH VOLTAGE

Frequency converters contain high voltage when connected to AC mains input, DC supply, or load sharing. Failure to perform installation, start-up, and maintenance by qualified personnel can result in death or serious injury.

- **Installation, start-up, and maintenance must be performed by qualified personnel only.**

⚠WARNING

UNINTENDED START

When the frequency converter is connected to AC mains, DC supply, or load sharing, the motor may start at any time. Unintended start during programming, service, or repair work can result in death, serious injury, or property damage. The motor can start via an external switch, a serial bus command, an input reference signal from the LCP, or after a cleared fault condition.
To prevent unintended motor start:

- **Disconnect the frequency converter from the mains.**
- **Press [Off/Reset] on the LCP before programming parameters.**
- **Fully wire and assembly the frequency converter, motor, and any driven equipment before connecting the frequency converter to AC mains, DC supply, or load sharing.**

⚠WARNING

DISCHARGE TIME

The frequency converter contains DC-link capacitors, which can remain charged even when the frequency converter is not powered. Failure to wait the specified time after power has been removed before performing service or repair work, could result in death or serious injury.

1. **Stop the motor.**
2. **Disconnect FC 51 from mains (and external DC supply, if present).**
3. **Wait for 4 minutes (M1, M2 and M3) and 15 min (M4 and M5) for discharge of the DC-link.**
4. **Disconnect DC bus terminals and brake terminals (if present).**
5. **Remove motor cable.**

⚠WARNING

LEAKAGE CURRENT HAZARD

Leakage currents exceed 3.5 mA. Failure to ground the frequency converter properly can result in death or serious injury.

- **Ensure the correct grounding of the equipment by a certified electrical installer.**

⚠WARNING

EQUIPMENT HAZARD

Contact with rotating shafts and electrical equipment can result in death or serious injury.

- **Ensure that only trained and qualified personnel perform installation, start up, and maintenance.**
- **Ensure that electrical work conforms to national and local electrical codes.**
- **Follow the procedures in this document.**

⚠CAUTION

INTERNAL FAILURE HAZARD

An internal failure in the frequency converter can result in serious injury, when the frequency converter is not properly closed.

- **Ensure that all safety covers are in place and securely fastened before applying power.**

NOTICE

HIGH ALTITUDES

For installation at altitudes above 2000 m, contact Danfoss regarding PELV.

NOTICE

Use on Isolated Mains

For details about the use of the frequency converter on isolated mains, refer to section *RFI Switch* in the design guide.

Follow the recommendations regarding the installation on IT-mains. Use relevant monitoring devices for IT-mains to avoid damage.

3 Programming

3.1 How to Programme

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3.1.1 Programming with MCT 10 Set-up Software

The frequency converter can be programmed from a PC via RS485 com-port by installing the MCT 10 Set-up Software.

This software can either be ordered using code number 130B1000 or downloaded from the Danfoss Web site: *www.danfoss.com/BusinessAreas/DrivesSolutions/software-download*

Refer to *VLT® Motion Control Tools MCT 10 Set-up Software, Operating Instructions*.

3.1.2 Programming with the LCP 11 or LCP 12

The LCP is divided into four functional groups:

1. Numeric display.
2. Menu key.
3. Navigation keys.
4. Operation keys and indicator lights (LEDs).

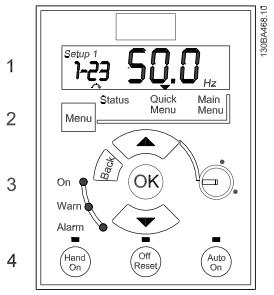

Illustration 3.1 LCP 12 with Potentiometer

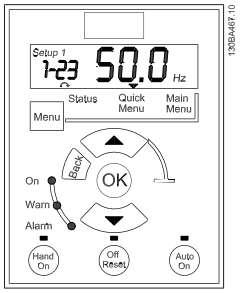

Illustration 3.2 LCP 11 without Potentiometer

The display
Different information can be read from the display.

Set-up number shows the active set-up and the edit set-up. If the same set-up acts as both active and edit set-up, only that set-up number is shown (factory setting). When active and edit set-up differ, both numbers are shown in the display (Set-up 12). The number flashing, indicates the edit set-up.

Illustration 3.3 Indicating Set-up

The small digits to the left are the selected parameter number.

Illustration 3.4 Indicating Selected Parameter Number

The large digits in the middle of the display show the value of the selected parameter.

Illustration 3.5 Indicating Value of Selected Parameter

The right side of the display shows the unit of the selected parameter. This can be either Hz, A, V, kW, hp, %, s or RPM.

Illustration 3.6 Indicating Unit of Selected Parameter

Motor direction is shown to the bottom left of the display - indicated by a small arrow pointing either clockwise or counterclockwise.

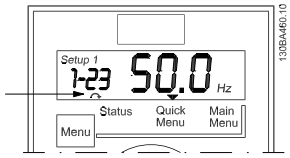

Illustration 3.7 Indicating Motor Direction

Press the [Menu] key to select one of the following menus

Status Menu
The Status Menu is either in *Readout Mode* or *Hand on Mode*. In *Readout Mode* the value of the currently selected readout parameter is shown in the display.

In *Hand on Mode* the local LCP reference is displayed.

Quick Menu
Displays Quick Menu parameters and their settings. Parameters in the Quick Menu can be accessed and edited from here. Most applications can be run by setting the parameters in the Quick Menus.

Main Menu
Displays Main Menu parameters and their settings. All parameters can be accessed and edited here.

LED (indicator lights)

- Green LED: The frequency converter is on.
- Yellow LED: Indicates a warning. See *chapter 6 Troubleshooting*.
- Flashing red LED: Indicates an alarm. See *chapter 6 Troubleshooting*.

Navigation keys
[Back]: For moving to the previous step or layer in the navigation structure.
[▲] [▼]: For maneuvering between parameter groups, parameters and within parameters.
[OK]: For selecting a parameter and for accepting changes to parameter settings.

Pressing [OK] for more than 1 s enters *Adjust* mode. In *Adjust* mode, it is possible to make fast adjustment by pressing [▲] [▼] combined with [OK].

Press [▲] [▼] to change value. Press [OK] to shift between digits quickly.

To exit *Adjust* mode, press [OK] more than 1 s again with changes saving or press [Back] without changes saving.

Operation keys
A yellow light above the operation keys indicates the active key.**[Hand On]:** Starts the motor and enables control of the frequency converter via the LCP.
[Off/Reset]: The motor stops except in alarm mode. In that case the motor will be reset.

[Auto On]: The frequency converter is controlled either via control terminals or serial communication.
[Potentiometer] (LCP 12): The potentiometer works in two ways depending on the mode in which the frequency converter is running.
In *Auto Mode* the potentiometer acts as an extra programmable analog input.
In *Hand on Mode* the potentiometer controls local reference.

3.2 Status Menu

After power up, the Status Menu is active. Press [Menu] to toggle between Status, Quick Menu and Main Menu.

[▲] and [▼] toggles between the choices in each menu.

The display indicates the status mode with a small arrow above “Status”.

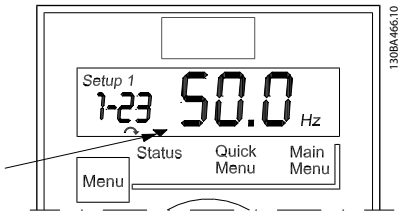

Illustration 3.8 Indicating Status Mode

3.3 Quick Menu

The Quick Menu gives easy access to the most frequently used parameters.

1. To enter the Quick Menu, press [Menu] key until indicator in display is placed above *Quick Menu*.
2. Press [▲] [▼] to select either QM1 or QM2, then press [OK].
3. Press [▲] [▼] to browse through the parameters in the Quick Menu.
4. Press [OK] to select a parameter.
5. Press [▲] [▼] to change the value of a parameter setting.
6. Press [OK] to accept the change.
7. To exit, press either [Back] twice to enter *Status*, or press [Menu] once to enter *Main Menu*.

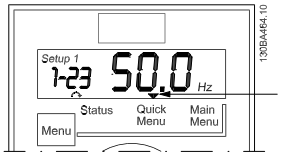

Illustration 3.9 Indicating Quick Menu Mode

3.4 Main Menu

The Main Menu gives access to all parameters.

1. To enter the Main Menu, press [Menu] key until indicator in display is placed above *Main Menu*.
2. Press [▲] [▼] to browse through the parameter groups.
3. Press [OK] to select a parameter group.
4. Press [▲] [▼] to browse through the parameters in the specific group.
5. Press [OK] to select the parameter.
6. Press [▲] [▼] to set/change the parameter value.
7. Press [OK] to accept the value.
8. To exit, press either [Back] twice to enter *Quick Menu*, or press [Menu] once to enter *Status*.

Illustration 3.10 Indicating Main Menu Mode

4 Parameter Descriptions

4.1 Parameter Group 0: Operation/Display

0-03 Regional Settings

Option:		Function:
		In order to meet the needs for different default settings in different parts of the world, *0-03 Regional Settings*, is implemented in the frequency converter. The selected setting influences the default setting of the motor nominal frequency.
[0] *	Interna-tional	Sets default of *1-23 Motor Frequency*, to 50 Hz, shows *1-20 Motor Power* in kW.
[1]	US	Sets default of *1-23 Motor Frequency*, to 60 Hz, shows *1-20 Motor Power* in HP. **NOTICE** **This parameter cannot be changed while motor runs.**

0-04 Operating State at Power-up (Hand Mode)

Option:		Function:
		This parameter controls whether or not the frequency converter start running the motor when powering up after a power down in Hand mode. **NOTICE** **If LCP with potentiometer is mounted, reference is set according to actual potentiometer value.**
[0]	Resume	Frequency converter starts in same Hand or Off State as when powered off. Local reference is stored and used after power-up.
[1] *	Forced Stop, Ref=Old	Frequency converter powers up in Off State meaning that motor is stopped after power up. Local reference is stored and used after power-up.
[2]	Forced Stop, Ref=0	Frequency converter powers up in Off State meaning that motor is stopped after power up. Local reference is set to 0. Thus motor will not start running before local reference has been increased.

4.1.1 0-1* Set-up Handling

User-defined parameters and miscellaneous external inputs (eg. bus, LCP, analog/digital inputs, feedback, etc.) controls the functionality of the frequency converter.

A complete set of all parameters controlling the frequency converter is called a set-up. The frequency converter contains 2 set-ups, *Set-up 1* and *Set-up 2*. Furthermore, a fixed set of factory settings can be copied into one or more set-ups.

Some of the advantages of having more than one set-up in the frequency converter are

- Run motor in one set-up (Active Set-up) while updating parameters in another set-up (Edit Set-up)
- Connect various motors (one at a time) to frequency converter. Motor data for various motors can be placed in different set-ups.
- Rapidly change settings of frequency converter and/or motor while motor is running (eg. ramp time or preset references) via bus or digital inputs.

The *Active Set-up* can be set as *Multi Set-up* where the active set-up is selected via input on a digital input terminal and/or via the bus control word.

NOTICE

Factory Set-up **cannot be used as active set-up.**

0-10 Active Set-up

Option:		Function:
		Active Set-up controls the motor. Shifts between set-ups can only happen when • the motor is coasted OR • the set-ups between which the shift happens are linked to each other (see *0-12 Linked Set-ups*). If changing between set-ups that are not linked, the change will not happen before motor is coasted. **NOTICE** **The motor is only considered stopped when it is coasted.**

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0-10 Active Set-up

Option:		Function:
[1] *	Set-up 1	*Set-up 1* is active.
[2]	Set-up 2	*Set-up 2* is active.
[9]	Multi Set-up	Select the active set-up via digital input and/or bus, see *5-1* Digital Inputs* choice [23].

0-11 Edit Set-up

Option:		Function:
		The *Edit Set-up* is for updating parameters in the frequency converter from either LCP or bus. It can be identical or different from the *Active Set-up*. All set-ups can be edited during operation, independently of the active set-up.
[1] *	Set-up 1	Update parameters in *Set-up 1*.
[2]	Set-up 2	Update parameters in *Set-up 2*.
[9]	Active Set-up	Update parameters in set-up selected as *Active Set-up* (see *0-10 Active Set-up*).

0-12 Link Set-ups

Option:		Function:
		The link ensures synchronizing of the "not changeable during operation" parameter values enabling shift from one set-up to another during operation. If the set-ups are not linked, a change between them is not possible while the motor is running. Thus the set-up change does not occur until the motor is coasted.
[0]	Not linked	Leaves parameters unchanged in both set-ups and cannot be changed while motor runs.
[1] *	Linked	Copy parameters "not changeable during operation" parameter values into presently selected *Edit Set-up*. ***NOTICE*** **This parameter cannot be changed while motor runs.**

0-31 Custom Readout Min Scale

Range:		Function:
0.00 *	[0.00–9999.00]	It is possible to create a customized readout related to the output frequency of the unit. The value entered in *0-31 Custom Readout Min Scale* will be shown at 0 Hz. The readout can be shown in the LCP display when in Status Mode or it can be read in *16-09 Custom Readout*

0-32 Custom Readout Max Scale

Range:		Function:
100.0*	[0.00–9999.00]	It is possible to create a customized readout related to the output frequency of the unit. The value entered in *0-32 Custom Readout Max Scale* will be shown at the frequency programmed in *4-14 Motor Speed High Limit*. The readout can be shown in the LCP display when in Status Mode or it can be read in *16-09 Custom Readout*

4.1.2 0-4* LCP

The frequency converter can operate in the following three modes: *Hand*, *Off* and *Auto*.
Hand: The frequency converter is locally operated and does not allow any remote control. By activating Hand a start signal is given.
OFF: The frequency converter stops with a normal stop ramp. When Off is chosen the frequency converter can only be started by pressing either Hand or Auto on the LCP.
Auto: In Auto-mode the frequency converter can be remote controlled (bus/digital).

0-40 [Hand On] Key on LCP

Option:		Function:
[0]	Disabled	[Hand On] key has no function.
[1] *	Enabled	[Hand On] key is functional.

0-41 [Off/Reset] Key on LCP

Option:		Function:
[0]	Disable Off/Reset	[Off/Reset] key has no function.
[1] *	Enable Off/Reset	Stop signal and reset of any faults.
[2]	Enable Reset Only	Reset only. Stop (Off) function is disabled.

0-42 [Auto On] Key on LCP

Option:		Function:
[0]	Disabled	[Auto On] key has no function.
[1] *	Enabled	[Auto On] key is functional.

4.1.3 0-5* Copy/Save

0-50 LCP Copy

Option:		Function:
		The detachable LCP of the frequency converter can be used for storing setups, and thus for transferring data when moving parameter settings from one frequency converter to another. ***NOTICE*** ***LCP Copy* can only be activated from the LCP and ONLY when the motor is coasted.**

0-50 LCP Copy

Option:		Function:
[0] *	No copy	
[1]	All to LCP	Copy all setups from the frequency converter into the LCP.
[2]	All from LCP	Copy all setups from LCP to frequency converter.
[3]	Size independent from LCP	Copy non motor size dependent data from LCP to frequency converter.

0-51 Set-up Copy

Option:		Function:
		Use this function to copy a set-up content into the *Edit Set-up*. In order to be able to make a set-up copy ensure that • the motor is coasted • *0-10 Active Set-up*, *Active Set-up*, is set to either *[1] Set-up 1* or *[2] Set-up 2* ***NOTICE*** **The keyboard/parameter database are blocked while Set-up Copy is running.**
[0] *	No Copy	Copy function is inactive
[1]	Copy from Set-up 1	Copy from *Set-up 1* to edit set-up chosen in *0-11 Edit Set-up*.
[2]	Copy from Set-up 2	Copy from *Set-up 2* to edit set-up chosen in *0-11 Edit Set-up*.
[9]	Copy from Factory Set-up	Copy from Factory Settings to edit set-up chosen in *0-11 Edit set-up*.

4.1.4 0-6* Password

0-60 (Main) Menu Password

Range:		Function:
		Use password for protection against unintended change of sensitive parameters, eg. motor parameters.
0 *	[0-999]	Enter the password for access to Main Menu via the [Main Menu] key. Select the number that should allow for changing other parameter values. *0* means there is no password.

NOTICE

A password has affect on the LCP - not on the bus communication.

NOTICE

Pressing [Menu], [OK] and [▼] will unlock the password. This will automatically enter the parameter editing screen in Quick Menu or Main Menu.

0-61 Access to Main/Quick Menu w/o Password

Option:		Function:
[0] *	Full access	Select *[0] Full Access* to disable the password in *0-60 (Main) Menu Password*.
[1]	LCP: Read Only	Select *[1] Read Only* to block unauthorized editing of Main/Quick menu parameter.
[2]	LCP: No Access	Select *[2] No Access* to block unauthorized editing and viewing of Main/Quick menu parameter.

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4.2 Parameter Group 1: Load/Motor

1-00 Configuration Mode

Option:		Function:
		Use this parameter for selecting the application control principle to be used when a Remote Reference is active. ***NOTICE*** **Changing this parameter resets *3-00 Reference Range*, *3-02 Minimum Reference* and *3-03 Maximum Reference* to their default values.** ***NOTICE*** **This parameter cannot be adjusted while motor runs.**
[0] *	Speed Open Loop	For normal speed control (References).
[3]	Process	Enables process closed loop control. See parameter group *7-3* Process PI Control* for further information on PI-controller.

1-01 Motor Control Principle

Option:		Function:
[0]	U/f	Is used for parallel connected motors and/or special motor applications. The U/f settings are set in *1-55 U/f Characteristic -U* and *1-56 U/f Characteristic -F*. ***NOTICE*** **When running U/f control slip- and load compensations are not included.**
[1] *	VVC+	Normal running mode, including slip- and load compensations.

1-03 Torque Characteristics

Option:		Function:
		With more torque characteristics it is possible to run low energy consuming, as well as high torque applications.
[0] *	Constant Torque	Motor shaft output provides constant torque under variable speed control.
[2]	Automatic Energy Optimisation	This function automatically optimizes energy consumption in centrifugal pump and fan applications. See *14-41 AEO Minimum Magnetisation*.

1-05 Hand Mode Configuration

Option:		Function:
		This parameter is only relevant when *1-00 Configuration Mode* is set to *[3] Process Closed Loop*. The parameter is used for determining the reference or setpoint handling when changing from Auto Mode to Hand Mode on the LCP.
[0]	Speed Open Loop	In Hand Mode the drive always runs in Open Loop configuration regardless of setting in *1-00 Configuration Mode*. Local potentiometer (if present) or Arrow up/down determines output frequency limited by Motor Speed High/Low Limit (*4-14 Motor Speed High Limit* and *4-12 Motor Speed Low Limit*).
[2] *	As configuration in *1-00 Configuration Mode*.	If *1-00 Configuration Mode* is set to *[1] Open Loop* function is as described above. If *1-00 Configuration Mode* is set to *[3] Process Closed Loop* changing from Auto mode to Hand mode results in a setpoint change via local potentiometer or Arrow up/down. The change is limited by Reference Max/Min (*3-02 Minimum Reference* and *3-03 Maximum Reference*).

4.2.1 1-2* Motor Data

Enter the correct motor nameplate data (power, voltage, frequency, current and speed).
Run AMT, see *1-29 Automatic Motor Tuning (AMT)*.
Factory settings for advanced motor data, parameter group *1-3* Adv. Motor Data*, are automatically calculated.

NOTICE

Parameters in parameter group *1-2* Motor Data* cannot be adjusted while motor runs.

1-20 Motor Power [kW]/[HP] ($P_{m.n}$)

Option:		Function:
		Enter motor power from nameplate data. Two sizes down, one size up from nominal VLT rating.
[1]	0.09 kW/0.12 HP	
[2]	0.12 kW/0.16 HP	
[3]	0.18kW/0.25 HP	
[4]	0.25 kW/0.33 HP	
[5]	0.37kW/0.50 HP	
[6]	0.55 kW/0.75 HP	
[7]	0.75 kW/1.00 HP	
[8]	1.10 kW/1.50 HP	
[9]	1.50 kW/2.00 HP	
[10]	2.20 kW/3.00 HP	
[11]	3.00 kW/4.00 HP	
[12]	3.70 kW/5.00 HP	
[13]	4.00 kW/5.40 HP	

1-20 Motor Power [kW]/[HP] ($P_{m.n}$)

Option:		Function:
[14]	5.50 kW/7.50 HP	
[15]	7.50 kW/10.0 HP	
[16]	11.00 kW/15.00 HP	
[17]	15.00 kW/20.00 HP	
[18]	18.50 kW/25.00 HP	
[19]	22.00 kW/29.50 HP	
[20]	30.00 kW/40.00 HP	

NOTICE

Changing this parameter affects parameters *1-22 Motor Voltage* to *1-25 Motor Frequency*, *1-30 Stator Resistance*, *1-33 Stator Leakage Reactance* and *1-35 Main Reactance*.

1-22 Motor Voltage ($U_{m.n}$)

Range:		Function:
230/400 V	[50-999 V]	Enter motor voltage from nameplate data.

1-23 Motor Frequency ($f_{m.n}$)

Range:		Function:
50 Hz*	[20-400 Hz]	Enter motor frequency from nameplate data.

1-24 Motor Current ($I_{m.n}$)

Range:		Function:
M-type dependent*	[0.01-100.00 A]	Enter motor current from nameplate data.

1-25 Motor Nominal Speed ($n_{m.n}$)

Range:		Function:
M-type Dependent*	[100–9999 RPM]	Enter motor nominal speed from nameplate data.

1-29 Automatic Motor Tuning (AMT)

Option:		Function:
		Use AMT to optimise motor performance. When *1-01 Motor Control Principle* is set to *[0] U/f*, AMT does not work. **NOTICE** **This parameter cannot be changed while the motor runs.** 1. Stop the frequency converter - make sure that the motor is at standstill 2. Select *[2] Enable AMT* 3. Apply start signal - Via LCP: Press [Hand On] - Or in Remote On mode: Apply start signal on terminal 18
[0] *	Off	AMT function is disabled.
[2]	Enable AMT	AMT function starts running.

1-29 Automatic Motor Tuning (AMT)

Option:		Function:
		NOTICE **To gain optimum tuning of the frequency converter, run AMT on a cold motor.**
[3]	Complete AMT with Rotating motor	**NOTICE** **When set to this option, the motor will rotate.** With this option, *1-35 Main Reactance (X2)* is also optimized, other than parameters *1-30 Stator Resistance (Rs)* and *1-33 Stator Leakage Reactance (X1)*.

4.2.2 1-3* Adv. Motor Data

Adjust advanced motor data using one of these methods:

1. Run AMT on cold motor. The frequency converter measures value from motor.
2. Enter X_1 value manually. Obtain value from motor supplier.
3. Use R_s, X_1, and X_2 default setting. The frequency converter establishes setting based on motor nameplate data.

NOTICE

These parameters cannot be changed while the motor runs.

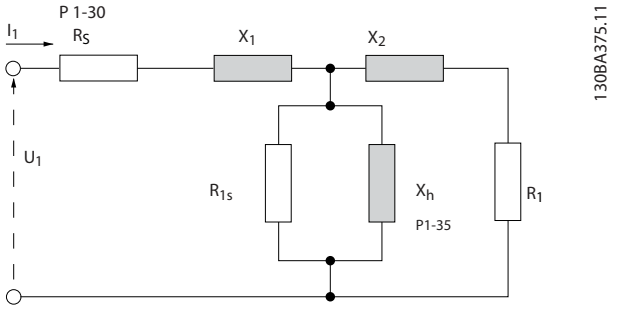

Illustration 4.1 Advanced Motor Data Parameters

1-30 Stator Resistance (R_s)

Range:		Function:
Depending on motor data*	[Ohm]	Set stator resistance value.

1-33 Stator Leakage Reactance (X_1)

Range:		Function:
Depending on motor data*	[Ohm]	Set stator leakage reactance of motor.

1-35 Main Reactance (X_2)

Range:		Function:
Depending on motor data*	[Ohm]	Set motor main reactance.

4.2.3 1-5* Load Independent Setting

This parameter group is for setting the load independent motor settings.

1-50 Motor Magnetization at Zero Speed

Range:		Function:
		This parameter enables different thermal load on motor when running at low speed.
100 %*	[0–300%]	Enter a percentage of rated magnetizing current. If setting is too low, motor shaft torque may be reduced.

1-52 Min. Speed Normal Magnetizing [Hz]

Range:		Function:
		Use this parameter along with *1-50 Motor Magnetizing at Zero Speed*.
0.0 Hz*	[0.0–10.0 Hz]	Set frequency required for normal magnetizing current. If frequency is set lower than motor slip frequency, *1-50 Motor Magnetizing at Zero Speed* is inactive.

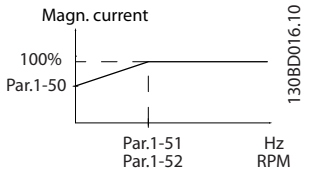

Illustration 4.2 Parameters 1-50 and 1-52

1-55 U/f Characteristic - U

Range:		Function:
		This parameter is an array parameter [0-5] and is only functional when *1-01 Motor Control Principle* is set to *[0] U/f*.
0.0 V*	[0.0–999.9 V]	Enter voltage at each frequency point to manually form a U/f characteristic matching motor. Frequency points are defined in *1-56 U/f characteristics - F*.

1-56 U/f Characteristic - F

Range:		Function:
		This parameter is an array parameter [0-5] and is only functional when *1-01 Motor Control Principle* is set to *[0] U/f*.
0.0 Hz*	[0.0–1000.0 Hz]	Enter frequency points to manually form a U/f characteristic matching motor. Voltage at each point is defined in *1-55 U/f Characteristic - U*. Make a U/f characteristic based on 6 definable voltages and frequencies, see *Illustration 4.3*.

1-56 U/f Characteristic - F

Range:		Function:
		Simplify U/f characteristics by merging 2 or more points (voltages and frequencies), respectively, are set equal.

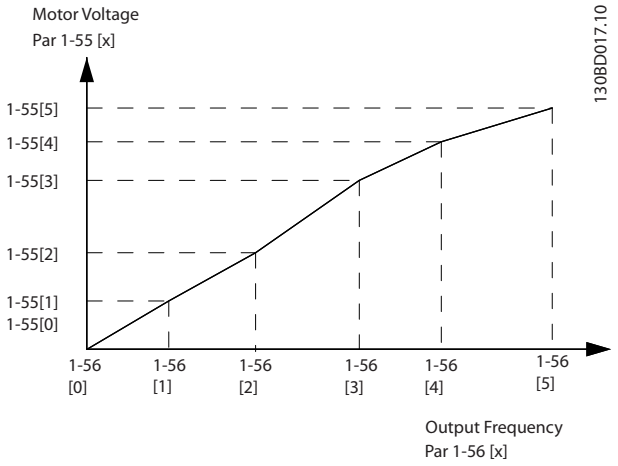

Illustration 4.3 U/f Characteristics

NOTICE

For *1-56 U/f characteristics - F* the following applies
[0] ≦ [1] ≦ [2] ≦ [3] ≦ [4] ≦ [5]

4.2.4 1-6* Load Dependent Setting

Parameters for adjusting the load-dependent motor settings.

1-60 Low Speed Load Compensation

Range:		Function:
		Use this parameter to gain optimum U/f characteristic when running at low speed.
100 %*	[0–199 %]	Enter percentage in relation to load when motor runs at low speed. Change-over point is automatically calculated based on motor size.

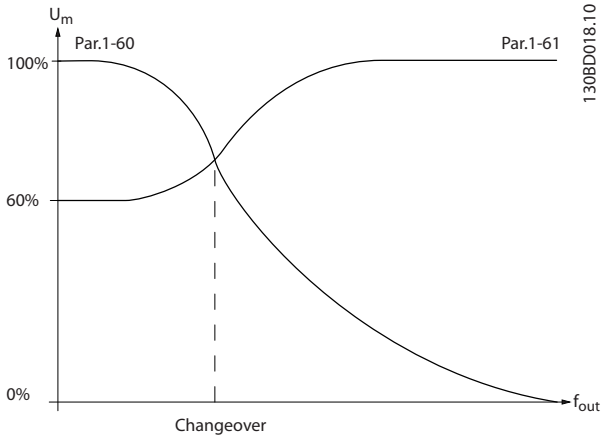

Illustration 4.4 Load Compensation Characteristics

1-61 High Speed Load Compensation

Range:		Function:
		Use this parameter to obtain optimum load compensation when running at high speed.
100 %*	[0–199 %]	Enter percentage to compensate in relation to load when motor runs at high speed. Change-over point is automatically calculated based on motor size.

1-62 Slip Compensation

Range:		Function:
100 %*	[-400–399 %]	Compensation for load dependent motor slip. Slip compensation is calculated automatically based on rated motor speed, $n_{M,N}$. ***NOTICE*** **This function is only active when *1-00 Configuration Mode*, is set to *[0] Speed Open Loop* and when *1-01 Motor Control Principle*, is set to *[1] VVC+*****

1-63 Slip Compensation Time

Range:		Function:
0.10 s	[0.05–5.00 s]	Enter slip compensation reaction speed. A high value results in slow reaction whereas a low value results in quick reaction. If low-frequency resonance problems arise, use longer time setting.

4.2.5 1-7* Start Adjustments

Considering the need for various start functions in different applications, it is possible to select a number of functions in this parameter group.

1-71 Start Delay

Range:		Function:
		The start delay defines the time to pass from a start command is given until the motor starts accelerating. Setting start delay to 0.0 s disables *1-72 Start Function*, when start command is given.
0.0 s*	[0.0–10.0 s]	Enter the time delay required before commencing acceleration. *1-72 Start Function* is active during *Start delay time*.

1-72 Start Function

Option:		Function:
[0]	DC Hold/Delay Time	Motor is energised with DC holding current (*2-00 DC Hold Current*) during start delay time.
[1]	DC Brake/ Delay Time	Motor is energised with DC braking current (*2-01 DC Brake Current*) during start delay time.
[2] *	Coast/Delay Time	Inverter is coasted during start delay time (inverter off).

1-73 Flying Start

Option:		Function:
		The Flying Start parameter is used to catch a spinning motor after eg. mains drop-out. ***NOTICE*** **This function is not suitable for hoisting applications.**
[0] *	Disabled	Flying start is not required.
[1]	Enabled	Frequency converter enabled to catch spinning motor. ***NOTICE*** **When flying start is enabled *1-71 Start Delay*, and *1-72 Start Function*, have no function.**

4.2.6 1-8* Stop Adjustments

To meet the need for various stop functions in different application these parameters offer some special stop features for the motor.

1-80 Function at Stop

Option:		Function:
		The selected function at stop is active in following situations: • Stop command is given and output speed is ramped down to *Min. Speed for Function at Stop*. • Start command is removed (standby), and output speed is ramped down to *Min. Speed for Function at Stop*.

4

1-80 Function at Stop

Option:		Function:
		• DC-brake command is given, and DC-brake time has passed • While running and calculated output speed is below *Min. Speed for Function at Stop*.
[0] *	Coast	The inverter is coasted.
[1]	DC hold	The motor is energised with a DC current. See *2-00 DC Hold Current* for more information.

1-82 Min. Speed For Function at Stop [Hz]

Range:		Function:
0.0 Hz*	[0.0–20.0 Hz]	Set the speed at which to activate *1-80 Function at Stop*.

4.2.7 1-9* Motor Temperature

With an estimated motor temperature monitor the frequency converter is able to estimate motor temperature without having a thermistor mounted. It is thus possible to receive a warning or an alarm, if motor temperature exceeds upper operational limit.

1-90 Motor Thermal Protection

Option:		Function:
		Using ETR (Electronic Terminal Relay) the motor temperature is calculated based on frequency, speed and time. Danfoss recommends using The ETR function, if a thermistor is not present. ***NOTICE*** **ETRElectronic Overload calculation is based on motor data from parameter group *1-2* Motor Data*.**
[0] *	No Protection	Disables temperature monitoring.
[1]	Thermistor Warning	A thermistor connected to either digital or analog input gives a warning if upper limit of motor temperature range is exceeded, (see *1-93 Thermistor Resource)*.
[2]	Thermistor Trip	A thermistor connected to either digital or analog input gives an alarm and makes the frequency converter trip if upper limit of motor temperature range is exceeded, (see *1-93 Thermistor Resource*.
[3]	ETR Warning	If calculated upper limit of motor temperature range is exceeded, a warning occurs.
[4]	ETR Trip	If 90% of calculated upper limit of motor temperature range is exceeded, an alarm occurs and the frequency converter trips.

NOTICE

When the ETR function has been selected the drive will store the recorded temperature at power down and this temperature will resume at power up regardless of the elapsed time. Changing *1-90 Motor Thermal Protection* back to *[0] No Protection* will reset the recorded temperature.

1-93 Thermistor Resource

Option:		Function:
		Select the thermistor input terminal.
[0] *	None	No thermistor is connected.
[1]	Analog Input 53	Connect thermistor to analog input terminal 53. ***NOTICE*** **Analog input 53 cannot be selected for other purposes when selected as thermistor resource.**
[6]	Digital input 29	Connect thermistor to digital input terminal 29. While this input functions as thermistor input, it will not respond to the function chosen in *5-13 Digital Input 29*. The value of *5-13 Digital Input 29* remains unchanged in parameter database while function is inactive.

Input Digital/ Analog	Supply Voltage	Threshold Cut-out Values
Digital	10 V	<800 Ω ⇒ 2.9 kΩ
Analog	10 V	<800 Ω ⇒ 2.9 kΩ

Table 4.1 Threshold Cut-out Values

4.3 Parameter Group 2: Brakes

4.3.1 2-0* DC-Brake

The purpose of DC-brake function is to brake a rotating motor by applying DC-current to the motor.

2-00 DC Hold Current

Range:		Function:
		This parameter either holds the motor (holding torque) or pre-heats the motor. The parameter is active if *DC Hold* has been selected in either *1-72 Start Function* or *1-80 Function at Stop*.
50%*	[0–150%]	Enter a value for holding current as a percentage of the rated motor current set in *1-24 Motor Current*. 100% DC holding current corresponds to $I_{M,N}$.

NOTICE

Avoid 100% current too long as it may overheat the motor.

2-01 DC Brake Current

Range:		Function:
50 %*	[0–150%]	Set DC-current needed to brake rotating motor. Activate DC-brake in one of the four following ways: 1. DC-brake command, see *5-1* Digital Inputs* choice [5] 2. DC Cut-in function, see *2-04 DC-Brake Cut-in Speed* 3. DC-brake selected as start function, see *1-72 Start Function* 4. DC-brake in connection with *Flying Start*, *1-73 Flying Start*.

2-02 DC-Braking Time

Range:		Function:
		DC-braking time defines the period during which *DC-brake current* is applied to the motor.
10.0 s*	[0.0–60 s]	Set the time DC-braking current, set in *2-01 DC Brake Current*, must be applied.

NOTICE

If DC-brake is activated as start function, DC-brake time is defined by *start delay time*.

2-04 DC-Brake Cut-in Speed

Range:		Function:
0.0 Hz*	[0.0–400.0 Hz]	Set DC-brake cut-in speed to activate DC braking current, set in *2-01 DC Brake Current*, when ramping down. When set to 0 the function is off.

4.3.2 2-1* Brake Energy Function

Use the parameters in this group for selecting dynamic braking parameters.

2-10 Brake Function

Option:		Function:
		NOTICE **Resistor brake is only functional in frequency converters with integrated dynamic brake. An external resistor must be connected.** **Resistor brake** The resistor brake limits voltage in the intermediate circuit when the motor acts as generator. Without brake resistor, the frequency converter eventually trips. The resistor brake consumes surplus energy resulting from motor braking. A frequency converter with brake, stops a motor faster than without a brake, which is used in many applications. Requires connection of external brake resistor. An alternative to the resistor brake is the AC brake. **AC brake** The AC brake consumes surplus energy by creating power loss in the motor. It is important to keep in mind that an increase in power loss causes motor temperature to rise.
[0] *	Off	No brake function.
[1]	Resistor Brake	Resistor brake is active.
[2]	AC Brake	AC brake is active.

2-11 Brake Resistor (Ohm)

Range:		Function:
5 Ω*	[5–5000 Ω]	Set brake resistor value.

2-14 Brake Voltage Reduce

Range:		Function:
0*	[0–100]	Change this parameter affects the value of *2-11 Brake Resistor (Ohm)*. Use this parameter to set the voltage reduction for resistor braking. It is only active when *2-10 Brake Function* is set to *[1] Resistor Brake*. This function is valid for 400 v, 5.5–15 kW units.

4

2-16 AC Brake, Max Current

Range:		Function:
100.0%*	[0.0–150.0%]	Enter max. permissible current for AC-braking to avoid overheating of motor. 100% equals motor current set in *1-24 Motor Current*.

2-17 Over-Voltage Control

Option:		Function:
		Use overvoltage control (OVC) to reduce the risk of the frequency converter tripping due to an over voltage on the DC link caused by generative power from the load. An over-voltage occurs eg. if the ramp down time is set too short compared to the actual load inertia.
[0] *	Disabled	The OVC is not active/required.
[1]	Enabled, not at stop	OVC is running unless a stop signal is active.
[2]	Enabled	OVC is running, also when a stop signal is active.

NOTICE

If Resistor Brake has been chosen in *2-10 Brake Function* the OVC is not active even though enabled in this parameter.

4.3.3 2-2* Mechanical Brake

For hoisting applications an electro-magnetic brake is required. The brake is controlled by a relay, which releases the brake when activated.

The brake activates if the frequency converter trips or a coast command is given. Furthermore, it activates when motor speed is ramped down below the speed set in *2-22 Active Brake Speed*.

2-20 Release Brake Current

Range:		Function:
0.00 A*	[0.00–100 A]	Select motor current at which mechanical brake releases. ***NOTICE*** **If start delay time has passed, and motor current is below *Release brake current*, frequency converter trips.**

2-22 Activating Mechanical Brake

Range:		Function:
		If the motor is stopped using ramp, the mechanical brake is activated when motor speed is less than *Active Brake Speed*. Motor is ramped down to stop in the following situations: • A start command is removed (stand by) • A stop command is activated • Quick-stop is activated (Q-stop ramp is used)
0 Hz*	[0–400 Hz]	Select motor speed at which mechanical brake activates when ramping down. Mechanical brake automatically activates if frequency converter trips or reports an alarm.

4.4 Parameter Group 3: Reference/Ramps

Parameters for reference handling, definition of limitations, and configuration of the frequency converter's reaction to changes

4.4.1 3-0* Reference Limits

Parameters for setting the reference unit, limits and ranges.

3-00 Reference Range

Option:		Function:
		Select the range of reference and feedback signals.
[0] *	Min to Max	Reference setpoint ranges can have positive values only. Select this if running in Process Closed Loop.
[1]	-Max to +Max	Ranges can have both positive and negative values. If potentiometer is used to adjust motor running in both direction, set reference range to –Max Reference to Max Reference by par.=[1] Choose hand on mode by LCP. Adjust the potentiometer to minimum, the motor can run in anti-clockwise with max speed. Then adjust the potentiometer to maximum, the motor will ramp down to 0 and run clockwise with max speed.

3-02 Minimum Reference

Range:		Function:
0.00*	[-4999-4999]	Enter value for minimum reference. The sum of all internal and external references are clamped (limited) to the minimum reference value, *3-02 Minimum Reference*.

3-03 Maximum Reference

Range:		Function:
		Maximum Reference is adjustable in the range Minimum Reference–4999.
60.000 Hz if parameter 0-03 is set to US; 50.000 Hz if parameter 0-03 is set to International *	[-4999–4999]	Enter value for Maximum Reference. The sum of all internal and external references are clamped (limited) to the maximum reference value, *3-03 Maximum Reference*.

4.4.2 3-1* References

Parameters for setting up the reference sources. Select the preset references for the corresponding digital inputs in parameter group, *5-1* Digital Inputs*.

3-10 Preset Reference

Option:		Function:
		Each parameter set-up contains 8 preset references which are selectable via 3 digital inputs or bus.

[18] Bit2	[17] Bit1	[16] Bit0	[16] Bit0
0	0	0	0
0	0	1	1
0	1	0	2
0	1	1	3
1	0	0	4
1	0	1	5
1	1	0	6
1	1	1	7

Table 4.2 Parameter Group 5-1* Digital Inputs Option [16], [17] and [18]

[0.00] *	-100.00–100.00%	Enter the different preset references using array programming. Normally, 100%=value set in *3-03 Maximum Reference*. However, there are exceptions if *3-00 Reference Range* is set to *[0] Min - Max*. Example 1: *3-02 Minimum Reference* is set to 20 and *3-03 Maximum Reference* is set to 50. In this case 0%=0 and 100%=50. Example 2: *3-02 Minimum Reference* is set to -70 and *3-03 Maximum Reference* is set to 50. In this case 0%=0 and 100%=70.

3-11 Jog Speed [Hz]

Range:		Function:
		Jog speed is a fixed output speed and overrules the selected reference speed, see parameter group *5-1* Digital Inputs* option [14]. If the motor is stopped while in jog mode, the jog signal acts as a start signal. Removing the jog signal makes the motor run according to the selected configuration.
5.0 Hz	[0.0–400.0 Hz]	Select speed to function as jog speed.

4

3-12 Catch Up/Slow Down Value

Range:		Function:
0% *	[0–100%]	The *Catch-up/Slowdown function* is activated by an input command (see *5-1* Digital Inputs*, choice [28]/[29]). If the command is active, the Catch-up/Slowdown value (in %) is added to the reference function as follows: $Reference = Reference + Reference \times \frac{Catchup\ Slowdown}{100}$ $Reference = Reference - Reference \times \frac{Catchup\ Slowdown}{100}$ When the input command is inactivated, the reference returns to its original value ie. Reference=Reference + 0.

3-14 Preset Relative Reference

Range:		Function:
0.00%	[-100.00–100.00%]	Define fixed value in % to be added to variable value defined in *3-18 Relative Scaling Reference Source*. The sum of fixed and variable values (labeled Y in illustration below) is multiplied with actual reference (labeled X in illustration). This product is added to actual reference $X + X \times \frac{Y}{100}$

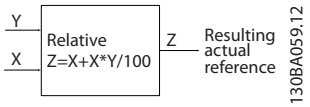

Illustration 4.5 Formula for Actual Reference

3-15 Reference 1 Source

Option:		Function:
		3-15 Reference 1 Source, *3-16 Reference 2 Source* and *3-17 Reference 3 Source* define up to three different reference signals. The sum of these reference signals defines the actual reference.
[0]	No Function	No reference signal is defined.
[1] *	Analog Input 53	Use signals from analog input 53 as reference, see parameter group *6-1* Analog Input 1*.
[2]	Analog Input 60	Use signals from analog input 60 as reference, see parameter group *6-2* Analog Input 2*.
[8]	Pulse input 33	Use signals from pulse input as reference, see parameter group *5-5* Pulse Input*.
[11]	Local Bus Reference	Use signals from local bus as reference, see parameter group *8-9* Bus Feedback*.
[21]	LCP Potentiometer	Use signals from LCP potentiometer as reference, parameter group *6-8* LCP Potentiometer*.

3-16 Reference 2 Source

Option:		Function:
		See *3-15 Reference 1 Source* for description.
[0]	No Function	No reference signal is defined.
[1]	Analog Input 53	Use signals from analog input 53 as reference.
[2] *	Analog Input 60	Use signals from analog input 60 as reference.
[8]	Pulse input 33	Use signals from pulse input as reference, see parameter group *5-5* Pulse Input*.
[11]	Local Bus Reference	Use signals from local bus as reference.
[21]	LCP Potentiometer	Use signals from LCP potentiometer as reference.

3-17 Reference 3 Source

Option:		Function:
		See *3-15 Reference 2 Source* for description.
[0]	No Function	No reference signal is defined.
[1]	Analog Input 53	Use signals from analog input 53 as reference.
[2]	Analog Input 60	Use signals from analog input 60 as reference.
[8]	Pulse input 33	Use signals from pulse input as reference, see parameter group *5-5* Pulse Input*.
[11] *	Local Bus Reference	Use signals from local bus as reference.
[21]	LCP Potentiometer	Use signals from LCP potentiometer as reference.

3-18 Relative Scaling Reference Source

Option:		Function:
		Select the source for a variable value to be added to the fixed value defined in *3-14 Preset Relative Reference*.
[0] *	No Function	The function is disabled
[1]	Analog Input 53	Select analog input 53 as relative scaling reference source.
[2]	Analog Input 60	Select analog input 60 as relative scaling reference source.
[8]	Pulse Input 33	Select pulse input 33 as relative scaling reference source.
[11]	Local Bus Reference	Select local bus ref. as relative scaling reference source.
[21]	LCP Potentiometer	Select LCP potentiometer as relative scaling reference source.

4.4.3 3-4* Ramp 1

A linear ramp is characterized by ramping up at a constant speed until the desired motor speed has been reached. Some overshoot may be experienced when reaching speed, which may cause speed jerks for a short while before stabilizing.
An S-ramp accelerates more smoothly thus compensating for jerks when the speed is reached.

See *Illustration 4.6* for a comparison of the two ramp types.

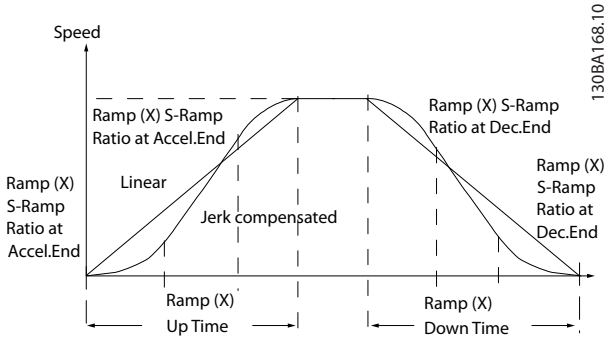

Illustration 4.6 Ramp Type Comparison

Ramp Times
Ramp up: Acceleration time from 0 to nominal motor frequency (*1-23 Motor Frequency*).
Deceleration time from nominal motor frequency (*1-23 Motor Frequency*) to 0.

Limitation
Too short ramp up time can result in Torque limit warning (W12) and/or DC over voltage warning (W7). Ramping is stopped when the frequency converter has reached Torque limit motor mode (*4-16 Torque Limit in Motor Mode*).
Too short ramp down time can result in Torque limit warning (W12) and/or DC over voltage warning (W7). Ramping is stopped when the frequency converter reaches the Torque limit generator mode (*4-17 Torque Limit in Generator Mode*) and/or the internal DC over voltage limit.

3-40 Ramp1 Type

Option:		Function:
[0] *	Linear	Constant acceleration/deceleration.
[2]	S-ramp	Smooth jerk compensated acceleration/ deceleration.

3-41 Ramp1 Ramp-up Time

Range:		Function:
Size related*	[0.05-3600.00 s]	Enter ramp-up time from 0 Hz to rated motor frequency ($f_{M,N}$) set in *1-23 Motor Frequency*. Select a ramp-up time ensuring that torque limit is not exceeded, see *4-16 Torque Limit in Motor Mode*.

3-42 Ramp1 Ramp-down Time

Range:		Function:
Size related*	[0.05-3600.00 s]	Enter ramp down time from rated motor frequency ($f_{M,N}$) in *1-23 Motor Frequency* to 0 Hz. Select a ramp down time that does not cause overvoltage in the inverter due to regenerative operation of motor. Furthermore, regenerative torque must not exceed limit set in *4-17 Torque Limit in Generator Mode*.

4.4.4 3-5* Ramp2

See parameter group *3-4* Ramp 1* for a description of ramp types.

NOTICE

Ramp2 - alternative ramp times:
Changing from Ramp1 to Ramp2 is done via the digital input. See *5-1* Digital Inputs*, option [34].

3-50 Ramp2 Type

Option:		Function:
[0] *	Linear	Constant acceleration/deceleration.
[2]	S-ramp	Smooth jerk compensated acceleration/ deceleration.

3-51 Ramp2 Ramp-up Time

Range:		Function:
Size related*	[0.05-3600.00 s]	Enter ramp-up time from 0 Hz to rated motor frequency ($f_{M,N}$) set in *1-23 Motor Frequency*. Choose a ramp-up time ensuring that torque limit is not exceeded, see *4-16 Torque Limit in Motor Mode*.

3-52 Ramp2 Ramp-down Time

Range:		Function:
Size related	[0.05-3600.00 s]	Enter ramp down time from rated motor frequency ($f_{M,N}$) in *1-23 Motor Frequency* to 0 Hz. Choose a ramp down time that does not cause over-voltage in inverter due to regenerative operation of motor. Furthermore, regenerative torque must not exceed limit set in *4-17 Torque Limit in Generator Mode*.

4.4.5 3-8* Other Ramps

This section contains parameters for Jog and Quick Stop Ramps.

With a Jog Ramp it is possible to both ramp up and down whereas, it is only possible to ramp down with the Quick Stop Ramp.

4

3-80 Jog Ramp Time

Range:		Function:
Size related*	[0.05-3600.00 s]	A linear ramp applicable when Jog is activated. See parameter group *5-1* Digital Inputs*, option [14]. Ramp up time = Ramp down time. Jog Ramp time starts upon activation of a jog signal via a selected digital input or serial communication port.

3-81 Quick Stop Ramp Time

Range:		Function:
Size related*	[0.05-3600.00 s]	A linear ramp applicable when Q-stop is activated. See parameter group *5-1* Digital Inputs*, option [4].

4.5 Parameter Group 4: Limits/Warnings

Parameter group for configuring limits and warning.

4.5.1 4-1* Motor Limits

Use these parameters for defining the speed, torque and current working range for the motor.

4-10 Motor Speed Direction

Option:		Function:
		If terminals 96, 97 and 98 are connected to U, V and W respectively, the motor runs clockwise when seen from the front. ***NOTICE*** **This parameter cannot be adjusted while the motor is running**
[0] *	Clockwise	The motor shaft rotates in clockwise direction. This setting prevents the motor from running in counterclockwise direction. If *1-00 Configuration Mode* is set to close loop control, *4-10 Motor Speed Direction* will be automatically set to clockwise.
[1]	Counter-clockwise	The motor shaft rotates in counterclockwise direction. This setting prevents the motor from running in clockwise direction.
[2] *	Both	With this setting the motor can run in both directions. However, the output frequency is limited to the range: Motor Speed Low Limit (*4-12 Motor Speed Low Limit*) to Motor Speed High Limit (*4-14 Motor Speed High Limit*). If *1-00 Configuration Mode* is set to open loop control, *4-10 Motor Speed Direction* will be automatically set to both direction

4-12 Motor Speed Low Limit

Range:		Function:
0.0 Hz*	[0.0-400.0 Hz]	Set the *Minimum Motor Speed Limit* corresponding to the minimum output frequency of the motor shaft. ***NOTICE*** **As the minimum output frequency is an absolute value, it cannot be deviated from.**

4-14 Motor Speed High Limit

Range:		Function:
65.0 Hz*	[0.0-400.0 Hz]	Set the *Maximum Motor Speed* corresponding to the maximum output frequency of the motor shaft. ***NOTICE*** **As the maximum output frequency is an absolute value, it cannot be deviated from.**

4-16 Torque Limit in Motor Mode

Range:		Function:
150 %*	[0-400%]	Set the torque limit for motor operation. The setting is not automatically reset to default when changing settings in *1-00 Configuration Mode* to *1-25 Load & Motor*.

4-17 Torque Limit in Generator Mode

Range:		Function:
100 %*	[0-400%]	Set the torque limit for generator mode operation. The setting is not automatically reset to default when changing settings in *1-00 Configuration Mode* to *1-25 Load & Motor*.

4.5.2 4-4* Adjustable Warnings 2

4-40 Warning Freq. Low

Range:		Function:
Size related*	[0 - 400 Hz]	Use this parameter to set a lower limit for the frequency range. When the motor speed drops below this limit, the display reads *SPEED LOW*. Warning bit 10 is set in *16-94 Ext. Status Word*. The output relay or the digital output can be configured to indicate this warning. The LCP warning indicator light is not turned on when this parameter set limit is reached.

4-41 Warning Freq. High

Use this parameter to set a higher limit for the frequency range. When the motor speed exceeds this limit, the display reads *SPEED HIGH*. Warning bit 9 is set in *16-94 Ext. Status Word*. The output relay or the digital output can be configured to indicate this warning. The LCP warning indicator light is not turned on when this parameter set limit is reached.

Range:		Function:
Size related*	[0 - 400 Hz]	

4.5.3 4-5* Adjustable Warnings

Parameter group containing adjustable warning limits for current, speed, reference and feedback.

Warnings are shown in display, programmed output or serial bus.

4

4-50 Warning Current Low

Range:		Function:
		Use this parameter to set a lower limit for the current range. If current drops below the set limit, warning bit 8 is set in *16-94 Ext. Status Word*. Output Relay can be configured to indicate this warning. LCP warning light does not light when this parameter's set limit is reached.
0.00 A*	[0.00–100.00A]	Set value for low current limit.

4-51 Warning Current High

Range:		Function:
		Use this parameter to set an upper limit for the current range. If current exceeds the set limit, warning bit 7 is set in *16-94 Ext. Status Word*. Output Relay can be configured to indicate this warning. LCP warning light does not light when this parameter's set limit is reached.
100.00 A*	[0.00–100.00 A]	Set upper current limit.

4-54 Warning Reference Low

Range:		Function:
-4999.000*	[-4999.000–Depends on the value of *4-55 Warning Reference High*]	Use this parameter to set a lower limit for the reference range. When the actual reference falls below this limit, the display reads Reference Low. Warning bit 20 is set in *16-94 Ext. Status Word*. Output Relay can be configured to indicate this warning. LCP warning light does not light when this parameter set limit is reached.

4-55 Warning Reference High

Range:		Function:
4999*	[-4999 - 4999]	Use this parameter to set a higher limit for the reference range. When the actual reference exceeds this limit, the display reads *Reference High*. Warning bit 19 is set in *16-94 Ext. Status Word*. The output relay or the digital output can be configured to indicate this warning. The LCP warning

4-55 Warning Reference High

Range:		Function:
		indicator light is not turned on when this parameter set limit is reached.

4-56 Warning Feedback Low

Range:		Function:
-4999*	[-4999 - 4999]	Use this parameter to set a lower limit for the feedback range. When the feedback drops below this limit, the display reads *Feedback Low*. Warning bit 6 is set in *16-94 Ext. Status Word*. The output relay or digital output can be configured to indicate this warning. The LCP warning indicator light does not light when this parameter set limit is reached.

4-57 Warning Feedback High

Range:		Function:
4999*	[-4999 - 4999]	Use this parameter to set a higher limit for the feedback range. When the feedback exceeds this limit, the display reads *Feedback High*. Warning bit 5 is set in *16-94 Ext. Status Word*. The output relay or digital output can be configured to indicate this warning. The LCP warning indicator light does not light when this parameter set limit is reached.

4-58 Missing Motor Phase Function

Option:		Function:
		A missing motor phase causes the motor torque to drop. This monitor may be disabled for special purposes (eg. small motors running pure U/f mode), but as there is a risk of overheating the motor, Danfoss strongly recommends that the function is On. A missing motor phase causes the frequency converter to trip and report an alarm. **NOTICE** **This parameter cannot be changed while motor runs.**
[0]	Off	Function is disabled.
[1] *	On	Function is enabled.

4.5.4 4-6* Speed Bypass

In some applications mechanical resonance may occur. Avoid resonance points by creating a bypass. The frequency converter ramps through the bypass area thereby passing mechanical resonance points quickly.

4-61 Speed Bypass From [Hz]

Array [2]

Range:		Function:
0.0 Hz*	[0.0–400.0 Hz]	Enter either the lower or upper limit of the speeds to be avoided. It does not matter whether Bypass From or Bypass To is the upper or lower limit, however the Speed Bypass function is disabled if the two parameters are set to the same value.

4-63 Speed Bypass To [Hz]

Array [2]

Range:		Function:
0.0 Hz*	[0.0–400.0 Hz]	Enter either the upper or lower limit of the speed area to be avoided. Make sure to enter the **opposite** limit of that in *4-61 Speed Bypass From [Hz]*.

4.6 Parameter Group 5: Digital In/Out

The following describes all digital input command functions and signals.

4.6.1 5-1* Digital Inputs

Parameters for configuring the functions for the input terminals.
The digital inputs are used for selecting various functions in the frequency converter. All digital inputs can be set to the following:

[0]	No Operation	The frequency converter will not react to signals transmitted to the terminal.
[1]	Reset	Reset the frequency converter after a Trip/ Alarm. Not all alarms can be reset.
[2]	Coast Inverse	Coasting stop, inverted input (NC). The frequency converter leaves the motor in free mode.
[3]	Coast and reset inv.	Reset and coasting stop inverted input (NC). The frequency converter resets and leaves the motor in free mode.
[4]	Quick stop inverse	Inverted input (NC). Generates a stop in accordance with the quick-stop ramp time set in *3-81 Quick Stop Ramp Time*. When motor stops, shaft is in free mode.
[5]	DC-brake inv.	Inverted input for DC braking (NC). Stops motor by energizing it with DC current for a certain time period, see *2-01 DC Brake Current*. Function is only active when value in *2-02 DC-Braking Time* is different from 0.
[6]	Stop inv.	Stop inverted function. Generates stop function when selected terminal goes from logical level “1” to “0”. Stop is performed according to selected ramp time.
[8]	Start	Select start for a start/stop command. 1 = Start, 0 = stop.
[9]	Latched start	Motor starts if a pulse is applied for min. 2 ms. Motor stops when Stop inverse is activated.
[10]	Reversing	Change direction of motor shaft rotation. Reversing signal only changes direction of rotation; it does not activate start function. Select *[2] Both directions* in *4.10 Motor Speed Direction*. 0 = normal, 1 = reversing.
[11]	Start reversing	Use for start/stop and for reversing at the same time. Signals on start [8] are not allowed at the same time. 0 = stop, 1 = start reversing.
[12]	Enable start forward	Use if motor shaft must rotate clockwise at start.
[13]	Enable start reverse	Use if motor shaft must rotate counter-clockwise at start.
[14]	Jog	Use for activating jog speed. See *3-11 Jog Speed*.
[16]	Preset reference bit 0	Preset reference bit 0, 1 and 2 enables a choice between one of the eight preset references according to below.
[17]	Preset reference bit 1	Same as preset reference bit 0 [16], see *3-10 Preset Reference*.
[18]	Preset reference bit 2	Same as preset reference bit 0 [16].
[19]	Freeze reference	Freeze actual reference. The frozen reference is now the point of enable/condition for Speed up and Speed down to be used. If Speed up/down is used, speed change always follows ramp 2 (*3-51 Ramp2 Ramp-up Time* and *3-52 Ramp2 Ramp-down Time*) in the range *3-02 Minimum Reference - 3-03 Maximum Reference*.
[20]	Freeze output	Freeze the actual motor frequency (Hz). The frozen motor frequency is now the point of enable/condition for Speed up and Speed down to be used. If Speed up/down is used, the speed change always follows ramp 2 in the range *4-12 Motor Speed Low Limit - 4-14 Motor Speed High Limit*. ***NOTICE*** **When freeze output is active, the frequency converter cannot be stopped via a low *[8] Start* signal. Stop the frequency converter via a terminal programmed for Coasting Inverse [2] or Coast and reset, inverse [3].**
[21]	Speed up	Select Speed up and Speed down if digital control of the up/down speed is desired (motor potentiometer). Activate this function by selecting either Freeze reference or Freeze output. When Speed-up is activated for less than 400 ms. the resulting reference will be increased by 0.1%. If Speed-up is activated for more than 400 ms. the resulting reference will ramp according to ramp 2 in *3-51 Ramp2 Ramp-up Time*.
[22]	Speed down	Same as Speed-up [21].
[23]	Setup select bit 0	Set *0-10 Active set-up* to Multi set-up. Logic 0 = set up 1, Logic 1 = Set up 2.
[28]	Catch up	Select Catch up/Slow down to increase or reduce the resulting reference value by the percentage set in *3-12 Catch Up/Slow Down Value*
[29]	Slow down	Same as Catch up [28]
[34]	Ramp bit 0	Logic 0=Ramp1, see parameter group *3-4* Ramp1* Logic 1=Ramp2, see parameter group *3-5* Ramp2*.

[60]	Counter A (up)	Input for counter A.
[61]	Counter A (down)	Input for counter A.
[62]	Reset counter A	Input for reset of counter A.
[63]	Counter B (up)	Input for counter B.
[64]	Counter B (down)	Input for counter B.
[65]	Reset counter B	Input for reset of counter B.

5-10 Terminal 18 Digital Input

Option:		Function:
[8] *	Start	Select function from available digital input range. See parameter group *5-1* Digital Inputs* for choices.

5-11 Terminal 19 Digital Input

Option:		Function:
[10] *	Reversing	Select function from available digital input range. See parameter group *5-1* Digital Inputs* for choices.

5-12 Terminal 27 Digital Input

Option:		Function:
[1] *	Reset	Select function from available digital input range. See parameter group *5-1* Digital Inputs** for choices.

5-13 Terminal 29 Digital Input

Option:		Function:
[14] *	Jog	Select function from available digital input range. See parameter group *5-1* Digital Inputs* for choices.

5-15 Terminal 33 Digital Input

Option:		Function:
[16] *	Preset bit 0	Select function from available digital input range. See parameter group *5-1* Digital Inputs* for choices.

4.6.2 5-3* Digital Outputs

5-34 On Delay, Digital Output

Enter the delay time before the digital output is switched on. The digital output (terminal 42/45) condition must not be interrupted during the delay time.

Range:		Function:
0.01 s*	[0 - 600 s]	

5-35 Off Delay, Digital Output

Enter the delay time before the digital output is switched off. The digital output (terminal 42/45) condition must not be interrupted during the delay time.

Range:		Function:
0.01 s*	[0 - 600 s]	

4.6.3 5-4* Relays

Parameter group for configuring timing and output functions for relays.

[0]	No Operation	Default for all digital and relay outputs.
[1]	Control Ready	Control board receives supply voltage.
[2]	Drive Ready	Frequency converter is ready for operation and applies supply signal on control board.
[3]	Drive Ready, Remote	Frequency converter is ready for operation in Auto On-mode.
[4]	Enable/No Warning	Frequency converter is ready for operation. No start or stop command is given. No warnings are present.
[5]	Drive Running	Motor is running.
[6]	Running/No Warning	Motor runs, and no warning are present.
[7]	Run in Range/No Warning	Motor runs within programmed current ranges, see *4-50 Warning Current Low* and *4-51 Warning Current High*. No warnings are present.
[8]	Run on ref/No Warning	Motor runs at reference speed.
[9]	Alarm	An alarm activates output.
[10]	Alarm on Warning	An alarm or warning activates output.
[12]	Out of Current Range	Motor current is outside range set in *4-50 Warning Current Low* and *4-51 Warning Current High*.
[13]	Below Current, low	Motor current is lower than set in *4-50 Warning Current Low*.
[14]	Above Current, high	Motor current is higher than set in *4-51 Warning Current High*.
[16]	Below Frequency, low	Motor speed is lower than set in *4-40 Warning Frequency Low*.
[17]	Above Frequency, high	Motor speed is higher than set in *4-41 Warning Frequency High*.
[19]	Below Feedback, low	Feedback is lower than set in *4-56 Warning Feedback Low*.
[20]	Above Feedback, high	Feedback is higher than set in *4-57 Warning Feedback High*.
[21]	Thermal Warning	Thermal warning is present when temperature exceeds limit in motor, frequency converter, brake resistor or thermistor.

[22]	Ready, No Thermal Warning	Frequency converter is ready for operation and no over-temperature warning is present.
[23]	Remote Ready, No Thermal Warning	Frequency converter is ready for operation in Auto mode, and no over-temperature warning is present.
[24]	Ready, Voltage OK	Frequency converter is ready for operation and mains voltage is within specified voltage range.
[25]	Reverse	Motor runs/is ready to run clockwise when logic = 0 and counter clockwise when logic = 1. Output changes as soon as reversing signal is applied.
[26]	Bus OK	Active communication (no time-out) via serial communication port.
[28]	Brake, No Warn	Brake is active, and no warnings are present.
[29]	Brake Ready/No Fault	Brake is ready for operation, and no faults are present.
[30]	Brake Fault (IGBT)	Protects frequency converter if fault on brake modules is present. Use relay to cut out main voltage from frequency converter.
[32]	Mech. Brake Control	Enables control of external mechanical brake, see parameter group *2-2* Mechanical Brake*.
[36]	Control Word Bit 11	Bit 11 in control word controls relay.
[41]	Below Reference, low	Reference is lower than set in *4-54 Warning Reference Low*.
[42]	Above Reference, high	Reference is higher than set in *4-55 Warning Reference High*.
[51]	Local Reference Active	
[52]	Remote Reference Active	
[53]	No Alarm	
[54]	Start Cmd Active	
[55]	Running Reverse	
[56]	Drive in Hand Mode	
[57]	Drive in Auto Mode	
[60]	Comparator 0	See parameter group *13-1* Comparators*. If comparator 0 is evaluated as TRUE, output goes high. Otherwise, it is low.
[61]	Comparator 1	See parameter group *13-1* Comparators*. If comparator 1 is evaluated as TRUE, output goes high. Otherwise, it is low.
[62]	Comparator 2	See parameter group *13-1* Comparators*. If comparator 2 is evaluated as TRUE, output goes high. Otherwise, it is low.
[63]	Comparator 3	See parameter group *13-1* Comparators*. If comparator 3 is evaluated as TRUE, output goes high. Otherwise, it is low.
[70]	Logic Rule 0	See parameter group *13-4* Logic Rules*. If Logic Rule 1 is evaluated as TRUE, output goes high. Otherwise, it is low.
[71]	Logic Rule 1	See parameter group *13-4* Logic Rules*. If Logic Rule 2 is evaluated as TRUE, output goes high. Otherwise, it is low.
[72]	Logic Rule 2	See parameter group *13-4* Logic Rules*. If Logic Rule 3 is evaluated as TRUE, output goes high. Otherwise, it is low.
[73]	Logic Rule 3	See parameter group *13-4* Logic Rules*. If Logic Rule 3 is evaluated as TRUE, output goes high. Otherwise, it is low.
[81]	SL Digital Output B	See *13-52 SL Control Action*. When Smart Logic Action *[39] Set dig. out. A high* is executed, input goes high. When Smart Logic Action *[33] Set dig. out. A low* is executed, input goes low.

5-40 Function Relay

Option:		Function:
[0] *	No Operation	Select function from available relay output range.

5-41 On delay, Relay

Option:		Function:
[0.01 s] *	0.00–600.00 s	Enter the delay of the relay cut-in time. If the Selected Event condition changes before the On delay timer expires, the relay output is unaffected. The function to control the relay see *5-40 Function Relay*.

5-42 Off delay, Relay

Option:		Function:
[0.01 s] *	0.00–600.00 s	Enter the delay of the relay cut-off time. If the Selected Event condition changes before the off delay timer expires, the relay output is unaffected. The function to control the relay see *5-40 Function Relay*.

4.6.4 5-5* Pulse Input

Set *5-15 Terminal 33 Digital Input* to choice *[32] pulse input*. Now terminal 33 handles a pulse input in the range from Low frequency, *5-55 Terminal 33 Low Frequency*, to *5-56 Terminal 33 High Frequency*. Scale frequency input via *5-57 Terminal 33 Low Ref./Feedb. Value* and *5-58 Terminal 33 High Ref./Feedb. Value*.

5-55 Terminal 33 Low Frequency

Range:		Function:
20 Hz*	[20–4999 Hz]	Enter low frequency corresponding to low motor shaft speed (i.e. low reference value) in *5-57 Terminal 33 Low Ref./Feedb. Value*.

5-56 Terminal 33 High Frequency

Range:		Function:
5000 Hz*	[21–5000 Hz]	Enter high frequency corresponding to high motor shaft speed (i.e. high reference value) in *5-58 Terminal 33 High Ref./Feedb. Value*.

5-57 Terminal 33 Low Ref./Feedb. Value

Range:		Function:
0.000*	[-4999–4999]	Set reference/feedback value corresponding to low pulse frequency value set in *5-55 Terminal 33 Low Frequency*.

5-58 Terminal 33 High Ref./Feedb. Value

Range:		Function:
60.000 Hz if parameter 0-03 is set to US; 50.000 Hz if parameter 0-03 is set to International*	[-4999-4999]	Set reference/feedback value corresponding to high pulse frequency value set in *5-56 Terminal 33 High Frequency*.

4.7 Parameter Group 6: Analog In/Out

Parameter group for configuring analog inputs and outputs.

4.7.1 6-0* Analog I/O Mode

Parameter group for setting up the analog I/O configuration.

6-00 Live Zero Timeout Time

Range:		Function:
		The Live Zero function is used for monitoring the signal on an analog input. If the signal disappears, a *Live Zero* warning is reported.
10 s*	[1–99 s]	Set delay time before *Live Zero Timeout Function* is applied (*6-01 Live Zero Timeout Time*). If the signal reappears during the set delay, timer will be reset. When live zero is detected, the frequency converter freezes output frequency and starts *Live Zero Timeout* timer.

6-01 Live Zero Timeout Function

Option:		Function:
		Function is activated if input signal is below 50% of value set in *6-10 Terminal 53 Low Voltage*, *6-12 Terminal 53 Low Current* or *6-22 Terminal 60 Low Current*.
[0] *	Off	Function is disabled.
[1]	Freeze output	Output frequency remains at value it had when live zero was detected.
[2]	Stop	Frequency converter ramps down to 0 Hz. Remove live zero error condition before restarting frequency converter.
[3]	Jogging	Frequency converter ramps to jog speed, see *3-11 Jog Speed*.
[4]	Max Speed	Frequency converter ramps to Motor Speed High Limit, see *4-14 Motor Speed High Limit*.
[5]	Stop and Trip	Frequency converter ramps down to 0 Hz and then trips. Remove live zero condition and activate reset before restarting the frequency converter.

4.7.2 6-1* Analog Input 1

Parameters for configuring scaling and limits for analog input 1 (terminal 53).

NOTICE

Micro switch 4 in position U:
***6-10 Terminal 53 Low Voltage* and *6-11 Terminal 53 High Voltage* are active.**
Micro switch 4 in position I:
***6-12 Terminal 53 Low Current* and *6-13 Terminal 53 High Current* are active.**

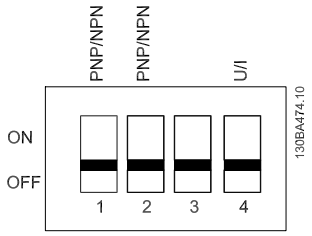

Illustration 4.7 S200 Switches 1–4

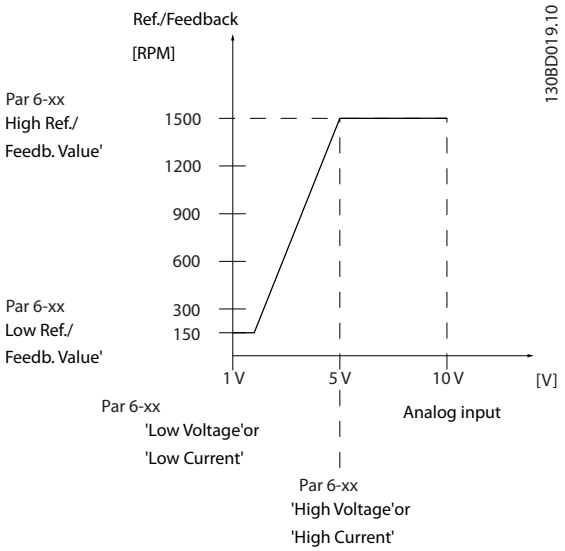

Illustration 4.8 Parameters for Configuring Analog Inputs

6-10 Terminal 53 Low Voltage

Range:		Function:
		NOTICE **The value must be set to min. 1 V in order to activate the Live Zero Timeout function in *6-01 Live Zero Timeout Function*.** This scaling value should correspond to minimum reference value set in *6-14 Terminal 53 Low Ref./Feedb. Value*. See also *chapter 4.4 Parameter Group 3: Reference/ Ramps*.
0.07 V*	[0.00–9.90 V]	Enter low voltage value.

6-11 Terminal 53 High Voltage

Range:		Function:
		This scaling value should correspond to maximum reference value set in *6-15 Terminal 53 High Ref./Feedb. Value*.
10.0 V*	[0.10–10.00 V]	Enter high voltage value.

6-12 Terminal 53 Low Current

Range:		Function:
		NOTICE **The value must be set to min. 2 mA in order to activate the Live Zero Timeout function in *6-01 Live Zero Timeout Function*.** This reference signal should correspond to minimum reference value set in *6-14 Terminal 53 Low Ref./Feedb. Value*.
0.14 mA*	[0.00–19.90 mA]	Enter the low current value.

6-13 Terminal 53 High Current

Range:		Function:
		This reference signal should correspond to the maximum reference value set in *6-15 Terminal 53 High Ref./Feedb. Value*.
20.00 mA*	[0.00–20.00 mA]	Enter high current value.

6-14 Terminal 53 Low Ref./Feedb. Value

Range:		Function:
		The scaling value corresponding to the low voltage/low current set in *6-10 Terminal 53 Low Voltage* and *6-12 Terminal 53 Low Current*.
0.000*	[-4999–4999]	Enter analog input scaling value.

6-15 Terminal 53 High Ref./Feedb. Value

Range:		Function:
		The scaling value corresponding to the high voltage/high current set in *6-11 Terminal 53 High Voltage* and *6-13 Terminal 53 High Current*.
60.000 Hz if parameter 0-03 is set to US; 50.000 Hz if parameter 0-03 is set to International *	[-4999.000–4999.000]	Enter analog input scaling value.

6-16 Terminal 53 Filter Time Constant

Range:		Function:
		A first-order digital low pass filter time constant for suppressing electrical noise in terminal 53. A high time constant value improves dampening but also increases time delay through the filter.
0.01 s*	[0.01–10.00 s]	Enter time constant.

6-19 Terminal 53 Mode

Option:		Function:
		Select the input to be present on terminal 53. ***NOTICE*** ***6-19 Terminal 53 Mode* MUST be set according to Micro switch 4 setting.**
[0] *	Voltage Mode	
[1]	Current Mode	

4.7.3 6-2* Analog Input 2

Parameters for configuring scaling and limits for analog input 2, terminal 60.

6-22 Terminal 60 Low Current

Range:		Function:
		NOTICE **The value must be set to min. 2 mA to activate the Live Zero Timeout function in *6-01 Live Zero Timeout Time*.** This reference signal should correspond to minimum reference value set in *6-24 Terminal 60 Low Ref./Feedb. Value*.
0.14 mA*	[0.00–20.00 mA]	Enter the low current value.

6-23 Terminal 60 High Current

Range:		Function:
		This reference signal should correspond to the high current value set in *6-25 Terminal 60 High Ref./Feedb. Value*.
20.00 mA*	[0.00–20.00 mA]	Enter high current value.

6-24 Terminal 60 Low Ref./Feedb. Value

Range:		Function:
		The scaling value corresponding to the low current set in *6-22 Terminal 60 Low Current*.
0.000*	[-4999–4999]	Enter analog input scaling value.

4

6-25 Terminal 60 High Ref./Feedb. Value

Range:		Function:
		The scaling value corresponding to the high current set in *6-23 Terminal 60 High Current*.
60.000 Hz if parameter 0-03 is set to US; 50.000 Hz if parameter 0-03 is set to International *	[-4999-4999]	Enter analog input scaling value.

6-26 Terminal 60 Filter Time Constant

Range:		Function:
		A first-order digital low pass filter time constant for suppressing electrical noise in terminal 60. A high time constant value improves dampening, but also increases time delay through the filter. ***NOTICE*** **This parameter cannot be changed while motor runs.**
0.01 s*	[0.01–10.00 s]	Enter time constant.

4.7.4 6-8* LCP Potentiometer

The LCP potentiometer can be selected either as Reference Resource or Relative Reference Resource.

NOTICE

In Hand mode, the LCP potentiometer functions as local reference.

6-80 LCP Potmeter Enable

Option:		Function:
		If LCP Potmeter is disabled, [▲] [▼] can adjust local reference, and Potmeter value does not give any reference in Auto/Hand mode.
[0]	Disabled	
[1] *	Enable	

6-81 LCP Potentiometer Low Ref. Value

Range:		Function:
		The scaling value corresponding to 0.
0.000*	[-4999–4999]	Enter low reference value. The reference value corresponding to potentiometer turned fully counter-clockwise (0 degrees).

6-82 LCP Potentiometer High Ref. Value

Range:		Function:
		The scaling value corresponding to the maximum reference feedback value set in *3-03 Maximum Reference*.
60.000 Hz if parameter 0-03 is set to US; 50.000 Hz if parameter 0-03 is set to International *	[-4999–4999]	Enter high reference value. The reference value corresponding to potentiometer turned fully clockwise (200 degrees).

4.7.5 6-9* Analog Output

These parameters are for configuring the analog outputs of the frequency converter.

6-90 Terminal 42 Mode

Option:		Function:
[0] *	0-20 mA	Range for analog outputs is 0-20 mA
[1]	4-20 mA	Range for analog outputs is 4-20 mA
[2]	Digital output	Functions as slow reacting digital output. Set value to either 0 mA (off) or 20 mA (on), see *6-92 Terminal 42 Digital Output*.

6-91 Terminal 42 Analog Output

Option:		Function:
		Select the function for terminal 42 as an analog output.
[0] *	No Operation	
[10]	Output Frequency [0-100 Hz]	
[11]	Reference (REF min-max)	*3-02 Minimum Reference* to *3-03 Minimum Reference*.
[12]	Feedback (FB min-max)	
[13]	Motor Current (0-I_{max})	*16-37 Inv. Max. Current* is I_{max}.
[16]	Power (0-P_{nom})	*1-20 Motor Power* is P_{nom} (motor).
[19]	DC Link Voltage (0–1000 V)	
[20]	Bus Reference [0.0% -100.0%]	The analog output will follow the reference value set on the RS-485 bus.

6-92 Terminal 42 Digital Output

Option:		Function:
		See parameter group *5-4* Relays*, for choices and descriptions.
[0] *	No Operation	
[80]	SL Digital Output A	See *13-52 SL Control Action*. When Smart Logic Action *[38] Set dig. out. A high* is executed, input goes high. When Smart Logic Action *[32] Set dig. out. A low* is executed, input goes low.

6-93 Terminal 42 Output Min. Scale

Range:		Function:
0.00%	[0.00-200.0%]	Scale minimum output of selected analog signal at terminal 42 as percentage of maximum signal value. E.g. if 0 mA (or 0 Hz) is desired at 25% of maximum output value, program 25%. Scaling values up to 100% can never be higher than corresponding setting in *6-94 Terminal 42 Output Min. Scale*.

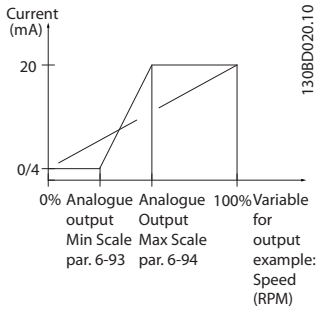

Illustration 4.9 Analog Output Parameters

6-94 Terminal 42 Output Max. Scale

Range:		Function:
100.00%*	[0.00–200.00%]	Scale maximum output of selected analog signal at terminal 42. Set value to maximum value of current signal output. Scale output to give a current lower than 20 mA at full scale; or 20 mA at an output below 100% of maximum signal value. If 20 mA is the desired output current at a value between 0-100% of the full-scale output, programme percentage value in the parameter, i.e. 50% = 20 mA. If a current between 4 and 20 mA is desired at maximum output (100%), calculate percentage value as follows: $\frac{20\ mA}{desired\ maximum\ current} \times 100\%$ i.e. $10\ mA = \frac{20}{10} \times 100 = 200\%$

4.8 Parameter Group 7: Controllers

Parameters group for configuring application controls.

4.8.1 7-2* Process Ctrl. Feedback

Select feedback sources and handling for Process PI Control.

4

NOTICE

Set *3-15 Reference 1 Source* to *[0] No Function* in order to use Analog Input as a feedback signal.
In order to use analog input as a feedback resource, do not use the same resource as reference resource in parameters 3-15, 3-16 and 3-17.

7-20 Process CL Feedback Resources

Option:		Function:
		Select input to function as feedback signal.
[0] *	No Function	
[1]	Analog Input 53	
[2]	Analog Input 60	
[8]	Pulse Input 33	
[11]	Local Bus	

4.8.2 7-3* Process PI Control

7-30 Process PI Normal/Inverse Control

Option:		Function:
[0] *	Normal	Feedback larger than setpoint results in a speed reduction. Feedback less than setpoint results in a speed increase.
[1]	Inverse	Feedback larger than setpoint results in a speed increase. Feedback less than setpoint results in a speed reduction.

7-31 Process PI Anti Windup

Option:		Function:
[0]	Disable	Regulation of a given error continues even when the output frequency cannot be increased/ decreased.
[1] *	Enable	PI-controller ceases from regulating a given error when the output frequency cannot be increased/ decreased.

7-32 Process PI Start Speed

Range:		Function:
0.0 Hz*	[0.0–200.0 Hz]	Until the set motor speed has been reached, the frequency converter operates in open loop mode.

7-33 Process PI Proportional Gain

Option:		Function:
[0.01] *	0.00–10.00	Enter the value for the P proportional gain, i.e. the multiplication factor of the error between the setpoint and the feedback signal. ***NOTICE*** **0.00=Off.**

7-34 Process PI Integral Time

Range:		Function:
9999.00 s*	[0.10–9999.00 s]	The integrator provides an increasing gain at a constant error between the set point and the feedback signal. The integral time is the time needed by the integrator to reach the same gain as the proportional gain.

7-38 Process Feed Forward Factor

Range:		Function:
0%*	[0–400%]	The FF factor sends a part of the reference signal around the PI controller which then only affects part of the control signal. By activating the FF factor less overshoot and high dynamics are gained when changing the setpoint. This parameter is always active when *1-00 Configuration Mode* is set to *[3] Process*.

7-39 On Reference Bandwidth

Range:		Function:
5%	[0–200%]	Enter the value for the On Reference Bandwidth. The PI control error is the difference between setpoint and feedback and when this is less than the value set in this parameter the On Reference is active.

4.9 Parameter Group 8: Communication

Parameter group for configuring communication.

4.9.1 8-0* General Settings

Use this parameter group for configuring the general settings for communication.

8-01 Control Site

Option:		Function:
[0] *	Digital and Control Word	Use both digital input and control word as control.
[1]	Digital Only	Use digital input as control.
[2]	Control Word Only	Use control word only as control. ***NOTICE*** **The setting in this parameter overrules settings in *8-50 Coasting Select* to *8-56 Preset Reference Select*.**

8-02 Control Word Source

Option:		Function:
[0]	None	Function is inactive
[1] *	FC RS-485	Monitoring control word source is done via serial communication port RS-485.

8-03 Control Word Timeout Time

Range:		Function:
1.0 s*	[0.1–6500 s]	Enter time to pass before control word timeout function (*8-04 Control Word Timeout Function*) must be carried out.

8-04 Control Word Timeout Function

Option:		Function:
		Select the action to be taken in case of a timeout.
[0] *	Off	No function.
[1]	Freeze Output	Freeze output until communication resumes.
[2]	Stop	Stop with auto restart when communication resumes.
[3]	Jogging	Run motor at jog frequency until communication resumes.
[4]	Max. Speed	Run motor at max. frequency until communication resumes.
[5]	Stop and Trip	Stop motor, then reset frequency converter in order to restart either via LCP or digital input.

8-06 Reset Control Word Timeout

Option:		Function:
		Resetting the control word timeout will remove any timeout function.
[0] *	No Function	Control word timeout is not reset.
[1]	Do Reset	Control word timeout is reset, and parameter goes into *[0] No Function* state.

4.9.2 8-3* FC Port Settings

Parameters for configuring the FC Port.

8-30 Protocol

Option:		Function:
		Select the protocol to be used. Note that changing protocol will not be effective until after powering off the frequency converter.
[0] *	FC	
[2]	Modbus RTU	

8-31 Address

Range:		Function:
		Select the address for the bus.
1*	[1 - Protocol-dependent]	FC-bus range is 1-126. Modbus range is 1-247.

8-32 FC Port Baud Rate

Option:		Function:
		Select baud rate for FC Port. ***NOTICE*** **Changing baud rate will be effective after responding to any ongoing bus-requests.**
[0]	2400 Baud	
[1]	4800 Baud	
[2] *	9600 Baud	When choosing FC bus in 8-30
[3] *	19200 Baud	When choosing Modbus in 8-30
[4]	38400 Baud	

8-33 FC Port Parity

Option:		Function:
		This parameter only affects Modbus as FC bus always has even parity.
[0] *	Even Parity (1 stopbit)	
[1]	Odd parity	
[2]	No Parity (1 stopbit)	
[3]	No Parity (2 stopbit)	

8-35 Minimum Response Delay

Range:		Function:
0.010 s*	[0.001-0.500 s]	Specify minimum delay time between receiving a request and transmitting a response.

8-36 Max Response Delay

Range:		Function:
5.000 s*	[0.010-10.00 s]	Specify maximum permissible delay time between transmitting a request and receiving a response. Exceeding this time delay causes control word timeout.

4

4.9.3 8-4* FC MC Protocol Set

8-42 FC Port PCD Write Configuration

Range:		Function:
Size related	[0–9999]	Select the parameters to be assigned to the telegrams of PCDs. The number of available PCDs depends on the telegram type. The values in PCDs are then written to the selected parameters as data values.
[0] *	None	
[1]	[302] Minimum Reference	
[2]	[303] Maximum Reference	
[3]	[312] Catch up/Slow Down Value	
[4]	[341] Ramp 1 Ramp up time	
[5]	[342] Ramp 1 Ramp down time	
[6]	[351] Ramp 2 Ramp up time	
[7]	[352] Ramp 2 Ramp down time	
[8]	[380] Jog Ramp Time	
[9]	[381] Quick Stop Time	
[10]	[412] Motor Speed Low Limit [Hz]	
[11]	[414] Motor Speed High Limit [Hz]	
[12]	[416] Torque Limit Motor Mode	
[13]	[417] Torque Limit Generator Mode	
[14]	FC Port CTW	
[15]	FC Port REF	

8-43 FC Port PCD Read Configuration

Array [16]

Option:		Function:
[0] *	None	
[1]	1500 Operation Hours	
[2]	1501 Running Hours	
[3]	1502 kWh Counter	
[4]	1600 Control Word	

8-43 FC Port PCD Read Configuration

Array [16]

Option:		Function:
[5]	1601 Reference [Unit]	
[6]	1602 Reference %	
[7]	1603 Status Word	
[8]	1605 Main Actual Value [%]	
[9]	1609 Custom Readout	
[10]	1610 Power [kW]	
[11]	1611 Power [hp]	
[12]	1612 Motor Voltage	
[13]	1613 Frequency	
[14]	1614 Motor Current	
[15]	1615 Frequency [%]	
[16]	1618 Motor Thermal	
[17]	1630 DC Link Voltage	
[18]	1634 Heatsink Temp.	
[19]	1635 Inverter Thermal	
[20]	1638 SL Controller State	
[21]	1650 External Reference	
[22]	1651 Pulse Reference	
[23]	1652 Feedback [Unit]	
[24]	1660 Digital Input 18,19,27,33	
[25]	1661 Digtial Input 29	
[26]	1662 Analog Input 53(V)	
[27]	1663 Analog Input 53(mA)	
[28]	1664 Analog Input 60	
[29]	1665 Analog Output 42 [mA]	
[30]	1668 Freq. Input 33 [Hz]	
[31]	1671 Relay Output [bin]	
[32]	1672 Counter A	
[33]	1673 Counter B	
[34]	1690 Alarm Word	
[35]	1692 Warning Word	
[36]	1694 Ext. Status Word	
		Select the parameters to be assigned to PCD's of telegrams. The number of available PCDs depends on the telegrams. This table is not for *[0] array* and *[1] array* . For these two arrays, index 1 is fixed to [7] and index 2 is fixed to [8]. These two arrays cannot be changed by end user.

4.9.4 8-5* Digital/Bus

Parameters for configuring control word Digital/Bus merging.

NOTICE

Parameters are only active when *8-01 Control Site*, is set to *[0] Digital and control word*.

8-50 Coasting Select

Option:		Function:
		Select control of coasting function via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

8-51 Quick Stop Select

Option:		Function:
		Select control of quick stop function via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

8-52 DC Brake Select

Option:		Function:
		Select control of DC brake via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

8-53 Start Select

Option:		Function:
		Select control of start function via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

8-54 Reversing Select

Option:		Function:
		Select control of reversing function via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

8-55 Set-up Select

Option:		Function:
		Select control of set-up selection via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

8-56 Preset Reference Select

Option:		Function:
		Select control of Preset Reference selection via digital input and/or bus.
[0]	Digital Input	Activation via a digital input.
[1]	Bus	Activation via serial communication port.
[2]	LogicAnd	Activation via serial communication port and a digital input.
[3] *	LogicOr	Activation via serial communication port or a digital input.

4.9.5 8-8* Bus communication diagnostics

These parameters are used for monitoring the Bus communication via the Port.

8-80 Bus Message Count

Range:		Function:
0 N/A*	[0-0 N/A]	This parameter shows the number of valid telegrams detected on the bus.

8-81 Bus Error Count

Range:		Function:
0 N/A*	[0-0 N/A]	This parameter shows the number of telegrams with faults (e.g. CRC fault), detected on the bus.

8-82 Slave Messages Rcvd

Range:		Function:
0 N/A*	[0-0 N/A]	This parameter shows the number of valid telegrams addressed to the slave, sent by the frequency converter.

8-83 Slave Error Count

Range:		Function:
0 N/A*	[0-0 N/A]	This parameter shows the number of error telegrams, which could be executed by the frequency converter.

4.9.6 8-9* Bus Feedback

4

Parameter for configuring bus feedback.

8-94 Bus Feedback 1

Range:		Function:
0*	[0x8000-0x7FFF]	Bus feedback is delivered via FC or Modbus by writing the feedback value into this parameter.

4.10 Parameter Group 13: Smart Logic

Smart Logic Control (SLC)is a sequence of user-defined actions (*13-52 SL Controller Action* [X]) executed by the SLC when the associated user-defined event (*13-51 SL Controller Event* [X]) is set to *True*.

Events and actions are linked in pairs, meaning that when an event is true, the linked action is carried out. After this the next event is evaluated and its belonging action carried out and so on. Only one event is evaluated at the time.

If an event is evaluated as *False*, the SLC takes no action during the scan interval and no other events are evaluated.

It is possible to programme from 1 to 20 events and actions.
When the last event/action has been executed, the sequence starts again from event/action [0].

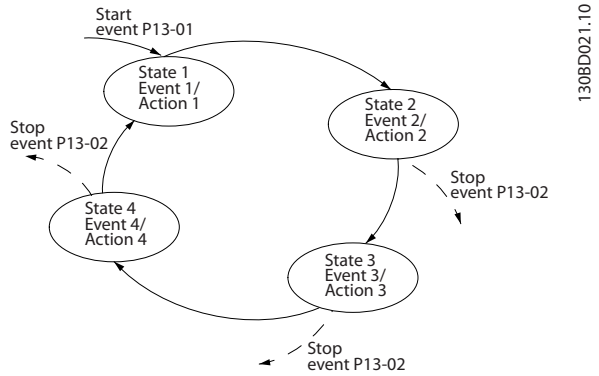

Illustration 4.10 Example with Three Events/Actions

Starting and stopping the SLC
Start the SLC by selecting *[1] On* in *13-00 SL Controller Mode* The SLC starts evaluating Event 0, and if this is evaluated as TRUE, the SLC continues its cycle.

The SLC stops when the *Stop Event*, *13-02 Stop Event*, is TRUE. The SLC can also be stopped by selecting *[0] Off* in *13-00 SL Controller Mode*.

To reset all SLC parameters select *[1] Reset SLC* in *13-03 Reset Smart Logic Controller* and start programming from scratch.

4.10.1 13-0* SLC Settings

Use SLC settings to activate, deactivate and reset the Smart Logic Control.

13-00 SL Controller Mode

Option:		Function:
[0] *	Off	Function is disabled.
[1]	On	SLC is active.

13-01 Start Event

Option:		Function:
		Select input to activate Smart Logic Control.
[0]	False	Enters *False* in logic rule.
[1]	True	Enters *True* in logic rule.
[2]	Running	See parameter group *5-4* Relays* [5] for description.
[3]	InRange	See parameter group *5-4* Relays* [7] for description.
[4]	OnReference	See parameter group *5-4* Relays* [8] for description.
[7]	Out of Current Range	See parameter group *5-4* Relays* [12] for description.
[8]	BelowILow	See parameter group *5-4* Relays* [13] for description.
[9]	AboveIHigh	See parameter group *5-4* Relays* [14] for description.
[16]	ThermalWarning	See parameter group *5-4* Relays* [21] for description.
[17]	MainsOutOfRange	Mains voltage is outside the specified voltage range.
[18]	Reversing	See parameter group *5-4* Relays* [25] for description.
[19]	Warning	A warning is active.
[20]	Alarm_Trip	A trip alarm is active.
[21]	Alarm_TripLock	A trip lock alarm is active.
[22]	Comparator 0	Use result of comparator 0 in logic rule.
[23]	Comparator 1	Use result of comparator 1 in logic rule.
[24]	Comparator 2	Use result of comparator 2 in logic rule.
[25]	Comparator 3	Use result of comparator 3 in logic rule.
[26]	LogicRule 0	Use result of logic rule 0 in logic rule.
[27]	LogicRule 1	Use result of logic rule 1 in logic rule.
[28]	LogicRule 2	Use result of logic rule 2 in logic rule.
[29]	LogicRule 3	Use result of logic rule 3 in logic rule.
[33]	DigitalInput_18	Use value of DI 18 in logic rule.
[34]	DigitalInput_19	Use value of DI 19 in logic rule.
[35]	DigitalInput_27	Use value of DI 27 in logic rule.
[36]	DigitalInput_29	Use value of DI 29 in logic rule.
[38]	DigitalInput_33	
[39] *	StartCommand	This event is *True*, if frequency converter is started by any means (digital input or other).
[40]	DriveStopped	This event is *True*, if frequency converter is stopped or coasted by any means (digital input or other).

4

13-02 Stop Event

Option:		Function:
		Select input to activate Smart Logic Control.
[0]	False	Enters *False* in logic rule.
[1]	True	Enters *True* in logic rule.
[2]	Running	See parameter group *5-4* Relays* [5] for description.
[3]	InRange	See parameter group *5-4* Relays* [7] for description.
[4]	OnReference	See parameter group *5-4* Relays* [8] for description.
[7]	Out of Current Range	See parameter group *5-4* Relays* [12] for description.
[8]	BelowILow	See parameter group *5-4* Relays* [13] for description.
[9]	AboveIHigh	See parameter group *5-4* Relays* [14] for description.
[16]	ThermalWarning	See parameter group *5-4* Relays* [21] for description.
[17]	MainsOutOfRange	Mains voltage is outside the specified voltage range.
[18]	Reversing	See parameter group *5-4* Relays* [25] for description.
[19]	Warning	A warning is active.
[20]	Alarm_Trip	A trip alarm is active.
[21]	Alarm_TripLock	A trip lock alarm is active.
[22]	Comparator 0	Use result of comparator 0 in logic rule.
[23]	Comparator 1	Use result of comparator 1 in logic rule.
[24]	Comparator 2	Use result of comparator 2 in logic rule.
[25]	Comparator 3	Use result of comparator 3 in logic rule.
[26]	LogicRule 0	Use result of logic rule 0 in logic rule.
[27]	LogicRule 1	Use result of logic rule 1 in logic rule.
[28]	LogicRule 2	Use result of logic rule 2 in logic rule.
[29]	LogicRule 3	Use result of logic rule 3 in logic rule.
[30]	SL Timeout0	Use result of timer 0 in logic rule.
[31]	SL Timeout1	Use result of timer 1 in logic rule.
[32]	SL Timeout2	Use result of timer 2 in logic rule.
[33]	DigitalInput_18	Use value of DI 18 in logic rule.
[34]	DigitalInput_19	Use value of DI 19 in logic rule.
[35]	DigitalInput_27	Use value of DI 27 in logic rule.
[36]	DigitalInput_29	Use value of DI 29 in logic rule.
[38]	DigitalInput_33	
[39]	StartCommand	This event is *True*, if frequency converter is started by any means (digital input or other).
[40] *	DriveStopped	This event is *True*, if frequency converter is stopped or coasted by any means (digital input or other).

13-03 Reset SLC

Option:		Function:
[0] *	Do Not Reset	Retains all settings programmed in parameter group 13.
[1]	Reset SLC	Reset all group 13 parameters to default settings.

4.10.2 13-1* Comparators

Comparators are used for comparing continuous variables (i.e. output frequency, output current, analog input etc.) to fixed preset values.

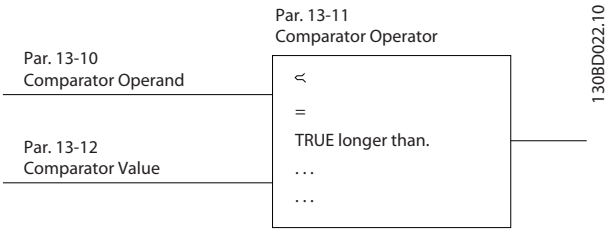

Illustration 4.11 Comparator Parameters

In addition, there are digital values that will be compared to fixed time values. See explanation in *13-10 Comparator Operand*. Comparators are evaluated once in each scan interval. Use the result (TRUE or FALSE) directly. All parameters in this parameter group are array parameters with index 0 to 5. Select index 0 toprogramme Comparator 0, select index 1 to programme Comparator 1, and so on.

13-10 Comparator Operand

Array [4]

Option:		Function:
		Select variable to be monitored by comparator.
[0] *	Disabled	Comparator is disabled.
[1]	Reference	Resulting remote reference (not local) as a percentage.
[2]	Feedback	Feedback in [Hz].
[3]	MotorSpeed	Motor speed in Hz.
[4]	MotorCurrent	Motor current in [A].
[6]	MotorPower	Motor power in either [kW] or [hp].
[7]	MotorVoltage	Motor voltage in [V].
[8]	DCLinkVoltage	DC-link voltage in [V].
[12]	AnalogInput53	Expressed as actual value.
[13]	AnalogInput60	Expressed as actual value.
[18]	PulseInput33	Expressed as actual value.
[20]	AlarmNumber	Shows number of the alarm.
[30]	CounterA	Number of counts.
[31]	CounterB	Number of counts.

13-11 Comparator Operator

Array [4]

Option:		Function:
		Select operator to be used in comparison.
[0]	Less Than <	Result of evaluation is *True* if variable selected in *13-10 Comparator Operand* is smaller than fixed value in *13-12 Comparator Value*. Result is *False* if variable selected in *13-10 Comparator Operand* is greater than fixed value in *13-12 Comparator Value*.
[1] *	Approxi-mately equals ≈	Result of evaluation is *True* if variable selected in *13-10 Comparator Operand* is approximately equal to fixed value in *13-12 Comparator Value*.
[2]	Greater Than >	Inverse logic of option [0].

13-12 Comparator Value

Array [4]

Range:		Function:
0.0*	[-9999-9999]	Enter "trigger level" for variable monitored by this comparator.

4.10.3 13-2* Timers

Use the timer results to define an event (*13-51 SL Controller Action*) or as boolean input in a logic rule (*13-40 Logic Rule Boolean 1*, *13-42 Logic Rule Boolean 2* or *13-44 Logic Rule Boolean 3*).

When timer value has elapsed timer changes state from *False* to *True*.

13-20 SLC Controller Timer

Array [3]

Range:		Function:
0.0 s*	[0.0-3600 s]	Enter value to define duration of the *False* output from programmed timer. A timer is only *False* if it is started by an action and until the given timer value has elapsed.

4.10.4 13-4* Logic Rules

Combine up to three boolean inputs (TRUE/FALSE inputs) from timers, comtors, digital inputs, status bits and events using the logical operators AND, OR, and NOT. Select boolean inputs for the calculation in *13-40 Logic Rule Boolean 1*, *13-42 Logic Rule Boolean 2* and *13-44 Logic Rule Boolean 3*. Define the operators used to logically combine the selected inputs in *13-41 Logic Rule Operator 1* and *13-43 Logic Rule Operator 2*.

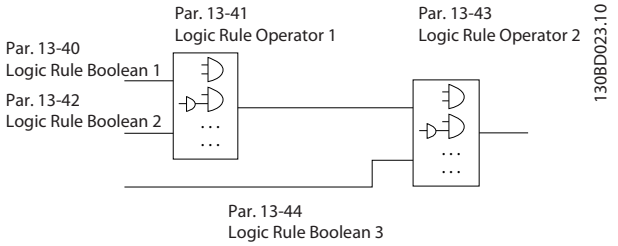

Illustration 4.12 Parameters for Logic Rules

Priority of calculation

The results of *13-40 Logic Rule Boolean 1*, *13-41 Logic Rule Operator 1* and *13-42 Logic Rule Boolean 2* are calculated first. The outcome (TRUE/FALSE) of this calculation is combined with the settings of *13-43 Logic Rule Operator 2* and *13-44 Logic Rule Boolean 3*, yielding the final result (TRUE/FALSE) of the logic rule.

13-40 Logic Rule Boolean 1

Array [4]

Option:		Function:
		Select first boolean input for selected logic rule.
[0] *	False	Enters *False* in logic rule.
[1]	True	Enters *True* in logic rule.
[2]	Running	See parameter group *5-4* Relays* [5] for description.
[3]	InRange	See parameter group *5-4* Relays* [7] for description.
[4]	OnReference	See parameter group *5-4* Relays* [8] for description.
[7]	Out of Current Range	See parameter group *5-4* Relays* [12] for description.
[8]	BelowlLow	See parameter group *5-4* Relays* [13] for description.
[9]	AbovelHigh	See parameter group *5-4* Relays* [14] for description.
[16]	ThermalWarning	See parameter group *5-4* Relays* [21] for description.
[17]	MainsOutOfRange	Mains voltage is outside the specified voltage range.
[18]	Reversing	See parameter group *5-4* Relays* [25] for description.
[19]	Warning	A warning is active.
[20]	Alarm_Trip	A trip alarm is active.
[21]	Alarm_TripLock	A trip lock alarm is active.
[22]	Comparator 0	Use result of comparator 0 in logic rule.
[23]	Comparator 1	Use result of comparator 1 in logic rule.
[24]	Comparator 2	Use result of comparator 2 in logic rule.
[25]	Comparator 3	Use result of comparator 3 in logic rule.
[26]	LogicRule 0	Use result of logic rule 0 in logic rule.

4

13-40 Logic Rule Boolean 1

Array [4]

Option:		Function:
[27]	LogicRule 1	Use result of logic rule 1 in logic rule.
[28]	LogicRule 2	Use result of logic rule 2 in logic rule.
[29]	LogicRule 3	Use result of logic rule 3 in logic rule.
[30]	SL Timeout0	Use result of timer 0 in logic rule.
[31]	SL Timeout1	Use result of timer 1 in logic rule.
[32]	SL Timeout2	Use result of timer 2 in logic rule.
[33]	DigitalInput_18	Use value of DI 18 in logic rule.
[34]	DigitalInput_19	Use value of DI 19 in logic rule.
[35]	DigitalInput_27	Use value of DI 27 in logic rule.
[36]	DigitalInput_29	Use value of DI 29 in logic rule.
[38]	DigitalInput_33	Use value of DI 33 in logic rule
[39]	StartCommand	This event is *True*, if frequency converter is started by any means (digital input or other).
[40]	DriveStopped	This event is *True*, if frequency converter is stopped or coasted by any means (digital input or other).

13-41 Logic Rule Operator 1

Array [4]

Option:		Function:
		Select first logical operator to use on boolean inputs from *13-40 Logic Rule Boolean 1* and *13-42 Logic Rule Boolean 2*.
[0] *	Disabled	Ignores *13-42 Logic Rule Boolean 2*, *13-43 Logic Rule Operator 2* and *13-44 Logic Rule Boolean 3*.
[1]	And	Evaluates expression [13-40] AND [13-42].
[2]	Or	Evaluates expression [13-40] OR [13-42].
[3]	And not	Evaluates expression [13-40] AND NOT [13-42].
[4]	Or not	Evaluates expression [13-40] OR NOT [13-42].
[5]	Not and	Evaluates expression NOT [13-40] and [13-42].
[6]	Not or	Evaluates expression NOT [13-40] OR [13-42].
[7]	Not and not	Evaluates expression NOT [13-40] AND NOT [13-42].
[8]	Not or not	Evaluates expression NOT [13-40] OR NOT [13-42].

13-42 Logic Rule Boolean 2

Array [4]

Option:		Function:
		Select second boolean input for selected logic rule. See *13-40 Logic Rule Boolean 1* for choices and descriptions.

13-43 Logic Rule Operator 2

Array [4]

Option:		Function:
		Select second logical operator to use on boolean inputs calculated in *13-40 Logic Rule Boolean 1*, *13-41 Logic Rule Operator 1*, and *13-42 Logic Rule Boolean 2* and the boolean input from *13-42 Logic Rule Boolean 2*.
[0] *	Disabled	Ignores *13-44 Logic Rule Boolean 3*.
[1]	And	Evaluates expression [13-40/13-42] AND [13-44].
[2]	Or	Evaluates expression [13-40/13-42] OR [13-44].
[3]	And not	Evaluates expression [13-40/13-42] AND NOT [13-44].
[4]	Or not	Evaluates expression [13-40/13-42] OR NOT [13-44].
[5]	Not and	Evaluates expression NOT [13-40/13-42] and [13-44].
[6]	Not or	Evaluates expression NOT [13-40/13-42] OR [13-44].
[7]	Not and not	Evaluates expression NOT [13-40/13-42] AND NOT [13-44].
[8]	Not or not	Evaluates expression NOT [13-40/13-42] OR NOT [13-44].

13-44 Logic Rule Boolean 3

Array [4]

Option:		Function:
		Select third boolean input for selected logic rule. See *13-40 Logic Rule Boolean 1* for choices and descriptions.

4.10.5 13-5* States

13-51 SL Controller Event

Array [20]

Option:		Function:
		Select boolean input to define Smart Controller Event. See *13-40 Logic Rule Boolean 1* for choices and descriptions.

13-52 SL Controller Action

Array [20]

Option:		Function:
		Select action corresponding to SLC event. Actions are executed when corresponding event (*13-51 SL Controller Event*) is evaluated as *True*.
[0] *	Disabled	Function is disabled.
[1]	No Action	No action is taken.
[2]	Select Set-up1	Changes active set-up to Set-up 1.
[3]	Select Set-up2	Changes active set-up to Set-up 2.
[10]	SelectPresetRef0	Selects preset reference 0
[11]	SelectPresetRef1	Selects preset reference 1
[12]	SelectPresetRef2	Selects preset reference 2
[13]	SelectPresetRef3	Selects preset reference 3
[14]	SelectPresetRef4	Selects preset reference 4

13-52 SL Controller Action

Array [20]

Option:		Function:
[15]	SelectPresetRef5	Selects preset reference 5
[16]	SelectPresetRef6	Selects preset reference 6
[17]	SelectPresetRef7	Selects preset reference 7
[18]	SelectRamp1	Selects ramp 1
[19]	SelectRamp2	Selects ramp 2
[22]	Run	Issues start command to frequency converter.
[23]	RunReverse	Issues start reverse command to frequency converter.
[24]	Stop	Issues stop command to frequency converter.
[25]	Qstop	Issues quick stop command to frequency converter.
[26]	DCstop	Issues DC stop command to frequency converter.
[27]	Coast	frequency converter coasts immediately. All stop commands including coast command stop the SLC.
[28]	Freeze Output	Freezes output frequency.
[29]	StartTimer0	Starts timer 0.
[30]	StartTimer1	Starts timer 1
[31]	StartTimer2	Starts timer 2
[32]	SetDO42Low	Set Digital output 42 low.
[33]	SetRelayLow	Set Relay low.
[38]	SetDO42High	Set Digital output 42 high.
[39]	SetRelayHigh	Set Relay high.
[60]	ResetCounterA	Resets counter A to 0.
[61]	ResetCounterB	Resets counter B to 0.

4.11 Parameter Group 14: Special Functions

Parameter group for configuring special frequency converter functions.

4.11.1 14-0* Inverter Switching

14-01 Switching Frequency

Option:		Function:
		Select the switching frequency in order to minimize e.g. acoustic noise and power loss or maximizing efficiency.
[0]	2 KHz	
[1] *	4 KHz	
[2]	8 KHz	
[4]	16 KHz	

NOTICE

For 18.5 kW and 22 kW frequency converter, the option [4] is not available.

14-03 Overmodulation

Option:		Function:
		This feature allows more accurate speed control near and over nominal speed (50/60 Hz). Another advantage with overmodulation is the ability of staying at a constant speed even though main is dropping.
[0]	Off	Disables the overmodulation function to avoid torque ripple on the motor shaft.
[1] *	On	Connects the overmodulation function to obtain an output voltage up to 15% greater than mains voltage.

4.11.2 14-1* Mains Monitoring

This parameter group supplies functions for handling imbalance on mains.

14-12 Functions at Mains Imbalance

Option:		Function:
		Operation under severe mains imbalance conditions reduces drive lift time. Select function to take place when severe mains imbalance is detected.
[0] *	Trip	Frequency converter trips.
[1]	Warning	Frequency converter issues a warning.
[2]	Disabled	No action taken.

Parameters for configuring auto reset handling, special trip handling and control card self-test or initialisation.

14-20 Reset Mode

Option:		Function:
		Select reset function after tripping. Once reset, the frequency converter can be restarted.
[0] *	Manual Reset	Perform reset via [Reset] or digital inputs.
[1]	AutoReset 1	Performs one automatic reset after tripping.
[2]	AutoReset 2	Performs two automatic resets after tripping.
[3]	AutoReset 3	Performs three automatic resets after tripping.
[4]	AutoReset 4	Performs four automatic resets after tripping.
[5]	AutoReset 5	Performs five automatic resets after tripping.
[6]	AutoReset 6	Performs six automatic resets after tripping.
[7]	AutoReset 7	Performs seven automatic resets after tripping.
[8]	AutoReset 8	Performs eight automatic resets after tripping.
[9]	AutoReset 9	Performs nine automatic resets after tripping.
[10]	AutoReset 10	Performs ten automatic resets after tripping.
[11]	AutoReset 15	Performs fifteen automatic resets after tripping.
[12]	AutoReset 20	Performs twenty automatic resets after tripping.
[13]	Infinite auto reset	Performs an infinite number of automatic resets after tripping.
[14]	Reset at power-up	Trip-lock alarm can be reset at power up. **⚠WARNING** **UNINTENDED START** **When the frequency converter is connected to AC mains, DC supply, or load sharing, the motor may start at any time. Unintended start during programming, service, or repair work can result in death, serious injury, or property damage. The motor can start via an external switch, a serial bus command, an input reference signal from the LCP, or after a cleared fault condition.** **To prevent unintended motor start:** • **Disconnect the frequency converter from the mains.** • **Press [Off/Reset] on the LCP before programming parameters.** • **Fully wire and assembly the frequency converter, motor, and any driven equipment before connecting the frequency converter to AC mains, DC supply, or load sharing.**

14-21 Automatic Restart Time

Range:		Function:
10 s*	[0-600 s]	Enter time interval from trip to start of automatic reset function. This parameter is active when *14-20 Reset Mode*, is set to *[1] to [13] Automatic Reset*.

14-22 Operation Mode

Option:		Function:
		Use this parameter for specifying normal operation or to initialize all parameters, except *15-03 Power Ups*, *15-04 Over Temps* and *15-05 Over Volts*.
[0] *	Normal Operation	Frequency converter runs normal operation.
[2]	Initialization	Resets all parameters to default settings, except for *15-03 Power Ups*, *15-04 Over Temps* and *15-05 Over Volts*. Frequency converter resets during next power-up. *14-22 Operation Mode* also reverts to default setting *[0] Normal Operation*.

14-26 Action at Inverter Fault

Option:		Function:
[0]	Trip	When the frequency converter detects an over-voltage, it will trip immediately. **NOTICE** **It is recommended to choose [0] Trip in hoisting applications.**
[1] *	Warning	When the frequency converter detects an over-voltage, it will give warning immediately. After protection filter, it will trip. **NOTICE** **It is recommended to disable *protection mode* in hoisting applications.**

4.11.3 14-4* Energy Optimising

Parameters for adjusting the energy optimisation level in both Variable Torque (VT) and AEOAutomatic Energy Saving mode.

14-41 AEO Minimum Magnetisation

Range:		Function:
66 %*	[40 - 75 %]	Enter the minimum allowable magnetisation for AEO. Selection of a low value reduces energy loss in the motor, but can also reduce resistance to sudden load changes.

4.11.4 14-9* Fault Settings

14-90 Fault Level

Use this parameter to customise fault levels. Only index 7, which indicates overcurrent faults, is supported.

Option:		Function:
[3] *	Trip lock	Alarm is set to trip lock level. Analog 13 overcurrent alarm cannot be reset without power cycle.
[4]	Trip w. delayed reset	Alarm is configured into trip alarm, which can be reset after a delay time. For example, if overcurrent alarm is configured to this option, it can be reset 3 minutes after the alarm is reported. Analog 13 overcurrent alarm is changed back to trip lock if it has been reset for more than 20 times.
[5]	Flystart	The frequency converter tries to catch a motor spinning when starting. If this option is selected, *1-73 Flying Start* s set to *[1] Enabled*.

4

4.12 Parameter Group 15: Drive Information

Parameter group containing information on operating data, hardware configuration, software version, etc.

15-00 Operating Time

Range:		Function:
0 days*	[0-9999 days]	View how many days the frequency converter has been powered up. The value is saved at power off and cannot be reset.

15-01 Running Hours

Range:		Function:
0*	[0- 60000]	View running hours of motor. The value is saved at power off and can be reset in *15-07 Reset Running Hours Counter*.

15-02 kWh Counter

Range:		Function:
0	[0-65535]	View power consumption in kWh as a mean value over one hour. Reset counter in *15-06 Reset kWh Counter*.

15-03 Power Ups

Range:		Function:
0	[0-2147483647]	View number of times frequency converter has been powered up. Counter cannot be reset.

15-04 Over Temps

Range:		Function:
0	[0-65535]	View number of times frequency converter has tripped due to over temperature. Counter cannot be reset.

15-05 Over Volts

Range:		Function:
0*	[0-65535]	View number of times frequency converter has tripped due to over voltage. Counter cannot be reset.

15-06 Reset kWh Counter

Option:		Function:
[0] *	Do Not Reset	Counter is not reset.
[1]	Reset Counter	Counter is reset.

15-07 Reset Running Hours Counter

Option:		Function:
[0] *	Do Not Reset	Counter is not reset.
[1]	Reset Counter	Counter is reset.

4.12.1 15-3* Fault Log

This parameter group contains a fault log showing reasons for the ten latest trips.

15-30 Fault Log: Error Code

Range:		Function:
0	[0-255]	View error code and look it up in *VLT® Micro Drive FC 51 Quick Guide*.

4.12.2 15-4* Drive Identification

Parameters containing read only information about the hardware and software configuration of the frequency converter.

15-40 FC Type

Option:		Function:
		View FC type.

15-41 Power Section

Option:		Function:
		View power section of frequency converter.

15-42 Voltage

Option:		Function:
		View voltage of frequency converter.

15-43 Software Version

Option:		Function:
		View software version of frequency converter.

15-46 Frequency Converter Ordering No

Option:		Function:
		View ordering number for re-ordering frequency converter in its original configuration.

15-48 LCP ID No

Option:		Function:
		View LCP ID number.

15-51 Frequency Converter Serial Number

Option:		Function:
		View frequency converter serial number.

4.13 Parameter Group 16: Data Readouts

16-00 Control Word

Range:		Function:
0*	[0-65535]	View latest valid control word sent to frequency converter via serial communication port.

16-01 Reference [Unit]

Range:		Function:
0.000*	[-4999.000-4999.000]	View total remote reference. Total reference is sum of pulse, analog, preset, LCP potentiometer, local bus and freeze reference.

16-02 Reference %

Range:		Function:
0.0*	[-200.0-200.0%]	View total remote reference in percent. Total reference is sum of pulse, analog, preset, LCP potentiometer, local bus and freeze reference.

16-03 Status Word

Range:		Function:
0*	[0-65535]	View status word sent to frequency converter via serial communication port.

16-05 Main Actual Value %

Range:		Function:
0.00*	[-100.00-100.00%]	View two-byte word sent with status word to bus Master reporting main actual value.

16-09 Custom Readout

Range:		Function:
0.00*	[0.00-9999.00%]	
		Customized readout based on the settings of *0-31 Custom Readout Min Scale*, *0-32 Custom Readout Max Scale* and *4-14 Motor Speed High Limit*

4.13.1 16-1* Motor Status

16-10 Power [kW]

Range:		Function:
0 kW*	[0-65.535 kW]	View output power in kW.

16-11 Power [hp]

Range:		Function:
0 hp	[0-65.535 hp]	View output power in hp.

16-12 Motor Voltage

Range:		Function:
0.0*	[0.0-65535 V]	View motor phase voltage.

16-13 Frequency

Range:		Function:
0.0 Hz*	[0.0-6553.5 Hz]	View output frequency in Hz.

16-14 Motor Current

Range:		Function:
0.00 A*	[0.00-655 A]	View motor phase current.

16-15 Frequency [%]

Range:		Function:
0.00*	[0-6553.5%]	View a two-byte word reporting actual motor frequency as a percentage of *4-14 Motor Speed High Limit*

16-18 Motor Thermal

Range:		Function:
0%*	[0-100%]	View calculated thermal motor load as percentage of estimated thermal motor load.

4.13.2 16-3* Drive Status

16-30 DC Link Voltage

Range:		Function:
0 V*	[0-65535 V]	View DC-link voltage.

16-34 Heat Sink Temp.

Range:		Function:
0*	[0-255°C]	View heat sink temperature of frequency converter.

16-35 Inverter Thermal

Range:		Function:
0%*	[0-255%]	View calculated thermal load on frequency converter in relation to estimated thermal load on frequency converter.

16-36 Inv. Nom. Current

Range:		Function:
0.00 A*	[0.00-655A]	View continuous nominal inverter current.

16-37 Inv. Max. Current

Range:		Function:
0.00 A*	[0.00-655A]	View intermittent maximum inverter current (150%).

16-38 SL Controller State

Range:		Function:
0*	[0-255]	View number of active SLC state.

4.13.3 16-5* Ref. & Feedb.

16-50 External Reference

Range:		Function:
0.0%*	[-200.0-200.0%]	View sum of all external references in percent.

16-51 Pulse Reference

Range:		Function:
0.0 %*	[-200.0-200.0%]	View actual pulse input converted to a reference in percent.

16-52 Feedback

Range:		Function:
0.000*	[-4999.000-4999.000]	View analog or pulse feedback in Hz.

4

4.13.4 16-6* Inputs and Outputs

16-60 Digital Input 18, 19, 27, 33

Range:		Function:
0*	[0-1111]	View signal states from active digital inputs.

16-61 Digital Input 29

Range:		Function:
0*	[0-1]	View signal state on digital input 29.

16-62 Analog Input 53 (volt)

Range:		Function:
0.00*	[0.00-10.00 V]	View input voltage on analog input terminal.

16-63 Analog Input 53 (current)

Range:		Function:
0.00*	[0.00-20.00 mA]	View input current on analog input terminal.

16-64 Analog Input 60

Range:		Function:
0.00*	[0.00-20.00 mA]	View actual value at input 60 either as reference or protection value.

16-65 Analog Output 42 [mA]

Range:		Function:
0.00 mA*	[0.00-20.00 mA]	View output current on analog output 42.

16-68 Pulse Input

Range:		Function:
20 Hz*	[20-5000 Hz]	View input frequency on pulse input terminal.

16-71 Relay Output [bin]

Range:		Function:
0*	[0-1]	View relay setting.

16-72 Counter A

Range:		Function:
0*	[-32768-32767]	View present value of Counter A.

16-73 Counter B

Range:		Function:
0*	[-32768-32767]	View present value of Counter B.

4.13.5 16-8* FC Port

Parameter for viewing references from FC Port.

16-86 FC Port REF 1

Range:		Function:
0*	[0x8000-0x7FFF]	View currently received reference from FC Port.

4.13.6 16-9* Diagnosis Read-Outs

16-90 Alarm Word

Range:		Function:
0*	[0-0xFFFFFFFF]	Via alarm word sent via serial communication port in hex code.

16-91 Alarm Word 2

Range:		Function:
0*	[0-0xFFFFFFFFUL]	View the alarm word 2 sent via the serial communication port in hex code.

16-92 Warning Word

Range:		Function:
0*	[0-0xFFFFFFFF]	View warning word sent via serial communication port in hex code.

16-94 Ext. Status Word

Range:		Function:
0*	[0-0xFFFFFFFF]	View extended warning word sent via serial communication port in hex code.

4.14 Parameter Group 18: Extended Motor Data

4.14.1 18-8* Motor Resistors

18-80 Stator Resistance (Rs in high resolution)

Range:		Function:
0.000 Ohm	[0.000–999.900 Ohm]	Set the stator resistance value. Enter the value from a motor data sheet or perform an AMT on a cold motor.

18-81 Stator Leakage Reactance (X1 in high resolution)

Range:		Function:
0.000 Ohm	[0.000–999.900 Ohm]	Set the stator leakage reactance value. Enter the value from a motor data sheet or perform an AMT on a cold motor. The default setting is calculated by the frequency converter from the motor nameplate data.

5 Parameter Lists

5.1 Parameter Overview

*0-** Operation/Display*
0-0 Basic Settings*
0-03 Regional Settings
*[0] International
[1] US
0-04 Oper. State at Power-up (Hand)
[0] Resume
*[1] Forced stop, ref=old
[2] Forced stop, ref=0
0-1 Set-up Handling*
0-10 Active Set-up
*[1] Set-up 1
[2] Set-up 2
[9] Multi Set-up
0-11 Edit Set-up
*[1] Set-up 1
[2] Set-up 2
[9] Active Set-up
0-12 Link Set-ups
[0] Not Linked
*[20] Linked
0-31 Custom Readout Min Scale
0.00–9999.00 * 0.00
0-32 Custom Readout Max Scale
0.00–9999.00 * 100.0
0-4 LCP Keypad*
0-40 [Hand on] Key on LCP
[0] Disabled
*[1] Enabled
0-41 [Off / Reset] Key on LCP
[0] Disable All
*[1] Enable All
[2] Enable Reset Only
0-42 [Auto on] Key on LCP
[0] Disabled
*[1] Enabled
0-5 Copy/Save*
0-50 LCP Copy
*[0] No copy
[1] All to LCP
[2] All from LCP
[3] Size indep. from LCP
0-51 Set-up Copy
*[0] No copy
[1] Copy from set-up 1
[2] Copy from set-up 2
[9] Copy from Factory set-up
0-6 Password*
0-60 (Main) Menu Password
0–999 *0

0-61 Access to Main/Quick Menu w/o Password
*[0] Full access
[1] LCP:Read Only
[2] LCP:No Access
*1-** Load/Motor*
1-0 General Settings*
1-00 Configuration Mode
*[0] Speed open loop
[3] Process
1-01 Motor Control Principle
[0] U/f
*[1] VVC+
1-03 Torque Characteristics
*[0] Constant torque
[2] Automatic Energy Optim.
1-05 Local Mode Configuration
[0] Speed Open Loop
*[2] As config in par. 1-00
1-2 Motor Data*
1-20 Motor Power [kW] [hp]
[1] 0.09 kW/0.12 hp
[2] 0.12 kW/0.16 hp
[3] 0.18 kW/0.25 hp
[4] 0.25 kW/0.33 hp
[5] 0.37 kW/0.50 hp
[6] 0.55 kW/0.75 hp
[7] 0.75 kW/1.00 hp
[8] 1.10 kW/1.50 hp
[9] 1.50 kW/2.00 hp
[10] 2.20 kW/3.00 hp
[11] 3.00 kW/4.00 hp
[12] 3.70 kW/5.00 hp
[13] 4.00 kW/5.40 hp
[14] 5.50 kW/7.50 hp
[15] 7.50 kW/10.00 hp
[16] 11.00 kW/15.00 hp
[17] 15.00 kW/20.00 hp
[18] 18.50 kW/25.00 hp
[19] 22.00 kW/29.50 hp
[20] 30.00 kW/40.00 hp
1-22 Motor Voltage
50-999 V *230–400 V
1-23 Motor Frequency
20–400 Hz *50 Hz
1-24 Motor Current
0.01–100.00 A *Motortype dep.
1-25 Motor Nominal Speed
100–9999 rpm *Motortype dep.

1-29 Automatic Motor Tuning (AMT)
*[0] Off
[2] Enable AMT
[3] Complete AMT with Rotating motor
1-3 Adv. Motor Data*
1-30 Stator Resistance (Rs)
[Ohm] * Dep. on motor data
1-33 Stator Leakage Reactance (X1)
[Ohm] * Dep. on motor data
1-35 Main Reactance (Xh)
[Ohm] * Dep. on motor data
1-5 Load Indep. Setting*
1-50 Motor Magnetisation at 0 Speed
0–300% *100%
1-52 Min Speed Norm. Magnet. [Hz]
0.0–10.0 Hz *0.0Hz
1-55 U/f Characteristic - U
0-999.9 V
1-56 U/f Characteristic - F
0-400 Hz
1-6 Load Depen. Setting*
1-60 Low Speed Load Compensation
0–199% *100%
1-61 High Speed Load Compensation
0–199% *100%
1-62 Slip Compensation
-400–399% *100%
1-63 Slip Compensation Time Constant
0.05–5.00 s *0.10 s
1-7 Start Adjustments*
1-71 Start Delay
0.0–10.0 s *0.0 s
1-72 Start Function
[0] DC hold/delay time
[1] DC brake/delay time
*[2] Coast/delay time
1-73 Flying Start
*[0] Disabled
[1] Enabled
1-8 Stop Adjustments*
1-80 Function at Stop
*[0] Coast
[1] DC hold

1-82 Min Speed for Funct. at Stop [Hz]
0.0–20.0 Hz *0.0 Hz
*1-9*Motor Temperature*
1-90 Motor Thermal Protection
*[0] No protection
[1] Thermistor warning
[2] Thermistor trip
[3] Etr warning
[4] Etr trip
1-93 Thermistor Resource
*[0] None
[1] Analog input 53
[6] Digital input 29
*2-** Brakes*
2-0 DC-Brake*
2-00 DC Hold Current
0–150% *50%
2-01 DC Brake Current
0–150% *50%
2-02 DC Braking Time
0.0–60.0 s *10.0 s
2-04 DC Brake Cut In Speed
0.0–400.0 Hz *0.0Hz
2-1 Brake Energy Funct.*
2-10 Brake Function
*[0] Off
[1] Resistor brake
[2] AC brake
2-11 Brake Resistor (ohm)
Min/Max/default: Powersize dep.
2-14 Brake Voltage reduce
0 - Powersize dep.* 0
2-16 AC Brake, Max current
0-150% *100%
2-17 Overvoltage Control
*[0] Disabled
[1] Enabled (not at stop)
[2] Enabled
2-2 Mechanical Brake*
2-20 Release Brake Current
0.00–100.0 A *0.00 A
2-22 Activate Brake Speed [Hz]
0.0–400.0 Hz *0.0 Hz
*3-** Reference / Ramps*
3-0 Reference Limits*
3-00 Reference Range
*[0] Min - Max
[1] -Max - +Max
3-02 Minimum Reference
-4999–4999 *0.000
3-03 Maximum Reference
-4999–4999 *50.00

1) M4 and M5 only

3-1 References*
3-10 Preset Reference
-100.0–100.0% *0.00% **3-11 Jog Speed [Hz]**
0.0–400.0 Hz *5.0 Hz
3-12 Catch up/slow Down Value
0.00–100.0% * 0.00%
3-14 Preset Relative Reference
-100.0–100.0% *0.00%
3-15 Reference Resource 1
[0] No function
*[1] Analog Input 53
[2] Analog input 60
[8] Pulse input 33
[11] Local bus ref
[21] LCP Potentiometer
3-16 Reference Resource 2
[0] No function
[1] Analog in 53
*[2] Analog in 60
[8] Pulse input 33
*[11] Local bus reference
[21] LCP Potentiometer
3-17 Reference Resource 3
[0] No function
[1] Analog Input 53
[2] Analog input 60
[8] Pulse input 33
*[11] Local bus ref
[21] LCP Potentiometer
3-18 Relative Scaling Ref. Resource
*[0] No function
[1] Analog Input 53
[2] Analog input 60
[8] Pulse input 33
[11] Local bus ref
[21] LCP Potentiometer
3-4 Ramp 1*
3-40 Ramp 1 Type
*[0] Linear
[2] Sine2 ramp
3-41 Ramp 1 Ramp up Time
0.05–3600 s *3.00 s (10.00 s[1)])
3-42 Ramp 1 Ramp Down Time
0.05–3600 s *3.00s (10.00s[1)])
3-5 Ramp 2*
3-50 Ramp 2 Type
*[0] Linear
[2] Sine2 ramp
3-51 Ramp 2 Ramp up Time
0.05–3600 s *3.00 s (10.00 s[1)])
3-52 Ramp 2 Ramp down Time
0.05–3600 s *3.00 s (10.00 s[1)])
3-8 Other Ramps*
3-80 Jog Ramp Time
0.05–3600 s *3.00 s (10.00s[1)])
3-81 Quick Stop Ramp Time
0.05–3600 s *3.00 s (10.00s[1)])
*4-** Limits/Warnings*
4-1 Motor Limits* **4-10 Motor Speed Direction**
*[0] Clockwise If Par. 1-00 is set to close loop control
[1] CounterClockwise
*[2] Both if Par. 1-00 is set to open loop control
4-12 Motor Speed Low Limit [Hz]
0.0–400.0 Hz *0.0 Hz
4-14 Motor Speed High Limit [Hz]
0.1–400.0 Hz *65.0 Hz
4-16 Torque Limit Motor Mode
0–400% *150%
4-17 Torque Limit Generator Mode
0–400% *100%
4-4* Adj. Warnings 2
4-40 Warning Frequency Low
0.00–Value of 4-41 Hz *0.0 Hz
4-41 Warning Frequency High
Value of 4-40–400.0 Hz *400.00 Hz
4-5* Adj. Warnings
4-50 Warning Current Low
0.00–100.00 A *0.00 A
4-51 Warning Current High
0.0–100.00 A *100.00 A
4-54 Warning Reference Low
-4999.000–Value of 4-55 * -4999.000
4-55 Warning Reference High
Value of 4-54–4999.000 *4999.000
4-56 Warning Feedback Low
-4999.000–Value of 4-57 * -4999.000
4-57 Warning Feedback High
Value of 4-56–4999.000 *4999.000
4-58 Missing Motor Phase Function
[0] Off
*[1] On
4-6 Speed Bypass*
4-61 Bypass Speed From [Hz]
0.0–400.0 Hz *0.0 Hz
4-63 Bypass Speed To [Hz]
0.0–400.0 Hz *0.0 Hz
5-1 Digital Inputs***5-10 Terminal 18 Digital Input**
[0] No function
[1] Reset
[2] Coast inverse
[3] Coast and reset inv.
[4] Quick stop inverse
[5] DC-brake inv.
[6] Stop inv
*[8] Start
[9] Latched start
[10] Reversing
[11] Start reversing
[12] Enable start forward
[13] Enable start reverse
[14] Jog
[16-18] Preset ref bit 0-2
[19] Freeze reference**5-10 Terminal 18 Digital Input**
[20] Freeze output
[21] Speed up
[22] Speed down
[23] Set-up select bit 0
[28] Catch up
[29] Slow down
[34] Ramp bit 0
[60] Counter A (up)
[61] Counter A (down)
[62] Reset counter A
[63] Counter B (up)
[64] Counter B (down)
[65] Reset counter B
5-11 Terminal 19 Digital Input
See par. 5-10. * [10] Reversing
5-12 Terminal 27 Digital Input
See par. 5-10. * [1] Reset
5-13 Terminal 29 Digital Input
See par. 5-10. * [14] Jog
5-15 Terminal 33 Digital Input
See par. 5-10. * [16] Preset ref bit 0
[26] Precise Stop Inverse
[27] Start, Precise Stop
[32] Pulse Input
5-3* Digital Outputs
5-34 On Delay, Terminal 42 Digital Output
0.00–600.00 s * 0.01 s
5-35 Off Delay, Terminal 42 Digital Output
0.00–600.00 s * 0.01 s
5-4 Relays*
5-40 Function Relay
[52] Remote ref. active
[53] No alarm
[54] Start cmd active
[55] Running reverse
[56] Drive in hand mode
[57] Drive in auto mode
[60-63] Comparator 0-3
[70-73] Logic rule 0-3
[81] SL digital output B
5-41 On Delay, Relay
0.00–600.00 s *0.01 s
5-42 Off Delay, Relay
0.00–600.00 s *0.01 s
5-5 Pulse Input*
5-55 Terminal 33 Low Frequency
20–4999 Hz *20 Hz
5-56 Terminal 33 High Frequency
21–5000 Hz *5000 Hz
5-57 Term. 33 Low Ref./Feedb. Value
-4999–4999 *0.000
5-58 Term. 33 High Ref./Feedb. Value
-4999–4999 *50.000
*6-** Analog In/Out*
6-0 Analog I/O Mode*
6-00 Live Zero Timeout Time
1-99 s *10 s
6-01 Live Zero TimeoutFunction
*[0] Off
[1] Freeze output
[2] Stop
[3] Jogging
[4] Max speed
[5] Stop and trip
6-1 Analog Input 1*
6-10 Terminal 53 Low Voltage
0.00–9.99 V *0.07 V
6-11 Terminal 53 High Voltage
0.01–10.00 V *10.00 V
6-12 Terminal 53 Low Current
0.00–19.99 mA *0.14 mA
6-13 Terminal 53 High Current
0.01–20.00 mA *20.00 mA
6-14 Term. 53 Low Ref./Feedb. Value
-4999-4999 *0.000
6-15 Term. 53 High Ref./Feedb. Value
-4999-4999 *50.000
6-16 Terminal 53 Filter Time Constant
0.01–10.00 s *0.01 s

1) M4 and M5 only

5

6-19 Terminal 53 mode
*[0] Voltage mode
[1] Current mode 4
6-2* Analog Input 2
6-22 Terminal 60 Low Current
0.00–19.99 mA *0.14 mA
6-23 Terminal 60 High Current
0.01–20.00 mA *20.00 mA
6-24 Term. 60 Low Ref./Feedb. Value
-4999-4999 *0.000
6-25 Term. 60 High Ref./Feedb. Value
-4999–4999 *50.00
6-26 Terminal 60 Filter Time Constant
0.01–10.00 s *0.01 s
6-8* LCP Potentiometer
6-80 LCP Potmeter Enable
[0] Disabled
*[1] Enable
6-81 LCP potm. Low Reference
-4999–4999 *0.000
6-82 LCP potm. High Reference
-4999–4999 *50.00
6-9* Analog Output xx
6-90 Terminal 42 Mode
*[0] 0-20 mA
[1] 4-20 mA
[2] Digital Output
6-91 Terminal 42 Analog Output
*[0] No operation
[10] Output Frequency
[11] Reference
[12] Feedback
[13] Motor Current
[16] Power
[19] DC Link Voltage
[20] Bus Reference
6-92 Terminal 42 Digital Output
See parameter 5-40
*[0] No Operation
[80] SL Digital Output A
6-93 Terminal 42 Output Min Scale
0.00-200.0% *0.00%
6-94 Terminal 42 Output Max Scale
0.00-200.0% *100.0%
7-** Controllers
7-2* Process Ctrl. Feedb
7-20 Process CL Feedback 1 Resource
*[0] NoFunction
[1] Analog Input 53
[2] Analog input 60
[8] PulseInput33
[11] LocalBusRef
7-3* Process PI
Ctrl. 7-30 Process PI Normal/ Inverse Ctrl
*[0] Normal
[1] Inverse
7-31 Process PI Anti Windup
[0] Disable
*[1] Enable
7-32 Process PI Start Speed
0.0–200.0 Hz *0.0 Hz
7-33 Process PI Proportional Gain
0.00–10.00 *0.01
7-34 Process PI Integral Time
0.10–9999 s *9999 s
7-38 Process PI Feed Forward Factor
0–400% *0%
7-39 On Reference Bandwidth
0–200% *5%
8-** Comm. and Options
8-0* General Settings
8-01 Control Site
*[0] Digital and ControlWord
[1] Digital only
[2] ControlWord only
8-02 Control Word Source
[0] None
*[1] FC RS485
8-03 Control Word Timeout Time
0.1–6500 s *1.0 s
8-04 Control Word Timeout Function
*[0] Off
[1] Freeze Output
[2] Stop
[3] Jogging
[4] Max. Speed
[5] Stop and trip
8-06 Reset Control Word Timeout
*[0] No Function
[1] Do reset
8-3* FC Port Settings
8-30 Protocol
*[0] FC
[2] Modbus
8-31 Address
1-247 *1
8-32 FC Port Baud Rate
[0] 2400 Baud
[1] 4800 Baud
*[2] 9600 Baud For choose FC Bus in 8-30
*[3] 19200 Baud For choose Modbus in 8-30
[4] 38400 Baud
8-33 FC Port Parity
*[0] Even Parity, 1 Stop Bit
[1] Odd Parity, 1 Stop Bit
[2] No Parity, 1 Stop Bit
[3] No Parity, 2 Stop Bits
8-35 Minimum Response Delay
0.001–0.5 *0.010 s
8-36 Max Response Delay
0.100–10.00 s *5.000 s
8-4* FC MC protocol set
8-43 FC Port PCD Read Configuration
*[0] None Expressionlimit
[1] [1500] Operation Hours
[2] [1501] Running Hours
[3] [1502] kWh Counter
[4] [1600] Control Word
[5] [1601] Reference [Unit]
[6] [1602] Reference %
[7] [1603] Status Word
[8] [1605] Main Actual Value [%]
[9] [1609] Custom Readout
[10] [1610] Power [kW]
[11] [1611] Power [hp]
[12] [1612] Motor Voltage
[13] [1613] Frequency
[14] [1614] Motor Current
[15] [1615] Frequency [%]
[16] [1618] Motor Thermal
[17] [1630] DC Link Voltage
[18] [1634] Heatsink Temp.
[19] [1635] Inverter Thermal
[20] [1638] SL Controller State
[21] [1650] External Reference
[22] [1651] Pulse Reference
[23] [1652] Feedback [Unit]
[24] [1660] Digital Input 18,19,27,33
[25] [1661] Digtial Input 29
[26] [1662] Analog Input 53 (V)
[27] [1663] Analog Input 53 (mA)
[28] [1664] Analog Input 60
[29] [1665] Analog Output 42 [mA]
[30] [1668] Freq. Input 33 [Hz]
[31] [1671] Relay Output [bin]
[32] [1672] Counter A
[33] [1673] Counter B
[34] [1690] Alarm Word
[35] [1692] Warning Word
[36] [1694] Ext. Status Word
8-5* Digital/Bus
8-50 Coasting Select
[0] DigitalInput
[1] Bus
[2] LogicAnd
*[3] LogicOr
8-51 Quick Stop Select
See par. 8-50 * [3] LogicOr
8-52 DC Brake Select
See par. 8-50 *[3] LogicOr
8-53 Start Select
See par. 8-50 *[3] LogicOr
8-54 Reversing Select
See par. 8-50 *[3] LogicOr
8-55 Set-up Select
See par. 8-50 *[3] LogicOr
8-56 Preset Reference Select
See parameter 8-50 * [3] LogicOr
8-8* Bus communication Diagnostics
8-80 Bus Message Count
0-0 N/A *0 N/A
8-81 Bus Error Count
0-0 N/A *0 N/A
8-82 Slave Messages Rcvd
0-0 N/A *0 N/A
8-83 Slave Error Count
0-0 N/A *0 N/A
8-9* Bus Jog / Feedback
8-94 Bus feedback 1
0x8000-0x7FFF *0
13-** Smart Logic
13-0* SLC Settings
13-00 SL Controller Mode
*[0] Off
[1] On
13-01 Start Event
[0] False
[1] True
[2] Running
[3] InRange
[4] OnReference
[7] OutOfCurrentRange
[8] BelowILow
[9] AboveIHigh
[16] ThermalWarning
[17] MainOutOfRange
[18] Reversing
[19] Warning
[20] Alarm_Trip
[21] Alarm_TripLock
[22-25] Comparator 0-3
[26-29] LogicRule0-3
[33] DigitalInput_18
[34] DigitalInput_19
[35] DigitalInput_27
[36] DigitalInput_29
[38] DigitalInput_33
*[39] StartCommand
[40] DriveStopped
13-02 Stop Event
See parameter 13-01 * [40] DriveStopped
13-03 Reset SLC
*[0] Do not reset
[1] Reset SLC

13-1 Comparators*
13-10 Comparator Operand
*[0] Disabled
[1] Reference
[2] Feedback
[3] MotorSpeed
[4] MotorCurrent
[6] MotorPower
[7] MotorVoltage
[8] DCLinkVoltage
[12] AnalogInput53
[13] AnalogInput60
[18] PulseInput33
[20] AlarmNumber
[30] CounterA
[31] CounterB
13-11 Comparator Operator
[0] Less Than
*[1] Approximately equals
[2] Greater Than
13-12 Comparator Value
-9999–9999 *0.0
13-2 Timers*
13-20 SL Controller Timer
0.0–3600 s *0.0 s
13-4 Logic Rules*
13-40 Logic Rule Boolean 1
See par. 13-01 *[0] False
[30] - [32] SL Time-out 0-2
13-41 Logic Rule Operator 1
*[0] Disabled
[1] And
[2] Or
[3] And not
[4] Or not
[5] Not and
[6] Not or
[7] Not and not
[8] Not or not
13-42 Logic Rule Boolean 2
See par. 13-40 * [0] False
13-43 Logic Rule Operator 2
See par. 13-41 *[0] Disabled
13-44 Logic Rule Boolean 3
See par. 13-40 * [0] False
13-5 States*
13-51 SL Controller Event
See par. 13-40 *[0] False
13-52 SL Controller Action
*[0] Disabled
[1] NoAction
[2] SelectSetup1
[3] SelectSetup2
[10-17] SelectPresetRef0-7
[18] SelectRamp1
[19] SelectRamp2
[22] Run
[23] RunReverse
[24] Stop
[25] Qstop
[26] DCstop
[27] Coast
[28] FreezeOutput
[29] StartTimer0
[30] StartTimer1
[31] StartTimer2
[32] Set Digital Output A Low
[33] Set Digital Output B Low
[38] Set Digital Output A High
[39] Set Digital Output B High
[60] ResetCounterA
[61] ResetCounterB
*14-** Special Functions*
14-0 Inverter Switching*
14-01 Switching Frequency
[0] 2 kHz
*[1] 4 kHz
[2] 8 kHz
[4] 16 kHz not available for M5
14-03 Overmodulation
[0] Off
*[1] On
14-1 Mains monitoring*
14-12 Function at mains imbalance
*[0] Trip
[1] Warning
[2] Disabled
14-2 Trip Reset*
14-20 Reset Mode
*[0] Manual reset
[1-9] AutoReset 1-9
[10] AutoReset 10
[11] AutoReset 15
[12] AutoReset 20
[13] Infinite auto reset
[14] Reset at power up
14-21 Automatic Restart Time
0–600s * 10s
14-22 Operation Mode
*[0] Normal Operation
[2] Initialisation **14-26 Action At Inverter Fault**
*[0] Trip
[1] Warning *14-4* Energy Optimising*
14-41 AEO Minimum Magnetisation
40–75 %*66 %
14-9* Fault Settings
14-90 Fault level[3] Trip Lock
[4] Trip with delayed reset
*15-** Drive Information*
15-0 Operating Data*
15-00 Operating Days
15-01 Running Hours
15-02 kWh Counter
15-03 Power Ups
15-04 Over Temps
15-05 Over Volts
15-06 Reset kWh Counter
*[0] Do not reset
[1] Reset counter
15-07 Reset Running Hours Counter
*[0] Do not reset
[1] Reset counter
15-3 Fault Log*
15-30 Fault Log: Error Code
15-4 Drive Identification*
15-40 FC Type
15-41 Power Section
15-42 Voltage
15-43 Software Version
15-46 Frequency Converter Order. No
15-48 LCP Id No
15-51 Frequency Converter Serial No
*16-** Data Readouts 16-0* General Status*
16-00 Control Word
0-0XFFFF
16-01 Reference [Unit]
-4999–4999 *0.000
16-02 Reference %
-200.0–200.0% *0.0%
16-03 Status Word
0–0XFFFF
16-05 Main Actual Value [%]
-200.0–200.0% *0.0%
16-09 Custom Readout
Dep. on par. 0-31, 0-32
16-1 Motor Status*
16-10 Power [kW]
16-11 Power [hp]
16-12 Motor Voltage [V]
16-13 Frequency [Hz]
16-14 Motor Current [A]
16-15 Frequency [%]
16-18 Motor Thermal [%]
16-3 Drive Status*
16-30 DC Link Voltage
16-34 Heat sink Temp.
16-35 Inverter Thermal
16-36 Inv.Nom. Current
16-37 Inv. Max. Current
16-38 SL Controller State
16-5 Ref./Feedb.*
16-50 External Reference
16-51 Pulse Reference
16-52 Feedback [Unit]
16-6 Inputs/Outputs*
16-60 Digital Input 18,19,27,33
0-1111
16-61 Digital Input 29
0-1
16-62 Analog Input 53 (volt)
16-63 Analog Input 53 (current)
16-64 Analog Input 60
16-65 Analog Output 42 [mA]
16-68 Pulse Input [Hz]
16-71 Relay Output [bin]
16-72 Counter A
16-73 Counter B
16-8 Fieldbus/FC Port*
16-86 FC Port REF 1
0x8000-0x7FFF
16-9 Diagnosis Readouts*
16-90 Alarm Word
0-0XFFFFFFFF
16-92 Warning Word
0-0XFFFFFFFF
16-94 Ext. Status Word
0-0XFFFFFFFF
*18-** Extended Motor Data*
18-8 Motor Resistors*
18-80 Stator Resistance (High resolution)
0.000–99.990 ohm *0.000 ohm
18-81 Stator Leakage Reactance(High resolution)
0.000–99.990 ohm *0.000 ohm

5.2 Parameter Lists

5.2.1 Conversion Index

The various attributes of each parameter are displayed in the section *Factory Settings*. Parameter values are transferred as whole numbers only. Conversion factors are therefore used to transfer decimals according to *Table 5.1*.

Example:
1-24 Motor Current has a conversion index of -2 (i.e. conversion factor of 0.01 according to *Table 5.1*). To set the parameter to 2.25 A, transfer the value 225 via Modbus. The Conversion Factor of 0.01 means that the value transferred is multiplied by 0.01 in the frequency converter. The vale 225 transferred on the bus is thus perceived as 2.25 A in the frequency converter.

Conversion index	Conversion factor
2	10
1	100
0	1
-1	0.1
-2	0.01
-3	0.001
-4	0.0001
-5	0.00001

Table 5.1 Conversion Table

5.2.2 Change During Operation

TRUE means that the parameter can be changed while the frequency converter is in operation and FALSE means that the frequency converter must be stopped before a change can be made.

5.2.3 2-Set-up

All set-up: The parameter can be set individually in each of the two set-ups, i.e. one single parameter can have two different data values.
1 set-up: Data value will be the same in both set-ups.

5.2.4 Type

Data type	Description	Type
2	Integer 8	Int8
3	Integer 16	Int16
4	Integer 32	Int32
5	Unsigned 8	Uint8
6	Unsigned 16	Uint16
7	Unsigned 32	Uint32
9	Visible string	VisibleString

Table 5.2 Type

5.2.5 0-** Operation/Display

Parameter number	Parameter description	Default value	2 Setup	Change during operation	Conversion index	Type
0-03	Regional Settings	[0] International	1 set-up	FALSE	-	Uint8
0-04	Operating State at Power-up (Hand)	[1] Forced stop ref=old	All set-ups	TRUE	-	Uint8
0-10	Active Set-up	[1] Set-up 1	1 set-up	TRUE	-	Uint8
0-11	Edit Set-up	[1] Set-up 1	1 set-up	TRUE	-	Uint8
0-12	Link Setups	[20] Linked	All set-ups	FALSE	-	Uint8
0-31	Custom Readout Min Scale	0	1 set-up	TRUE	-2	Int32
0-32	Custom Readout Max Scale	0	1 set-up	TRUE	-2	Int32
0-40	[Hand On] Key on LCP	[1] Enabled	All set-ups	TRUE	-	Uint8
0-41	[Off / Reset] Key on LCP	[1] Enable All	All set-ups	TRUE	-	Uint8
0-42	[Auto on] Key on LCP	[1] Enabled	All set-ups	TRUE	-	Uint8
0-50	LCP Copy	[0] No copy	1 set-up	FALSE	-	Uint8
0-51	Set-up Copy	[0] No copy	1 set-up	FALSE	-	Uint8
0-60	Main Menu Password	0	1 set-up	TRUE	0	Uint16
0-61	Access to Main/Quick menu w/o Password	0	1 set-up	TRUE	-	Uint8

5.2.6 1-** Load/Motor

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
1-00	Configuration Mode	[0] Speed open loop	All set-ups	TRUE	-	Uint8
1-01	Motor Control Principle	[1] VVC+	All set-ups	FALSE	-	Uint8
1-03	Torque Characteristics	[0] Constant torque	All set-ups	TRUE	-	Uint8
1-05	Hand Mode Configuration	[2] As mode *1-00 Configuration Mode*	All set-ups	TRUE	-	Uint8
1-20	Motor Power		All set-ups	FALSE	-	Uint8
1-22	Motor Voltage		All set-ups	FALSE	0	Uint16
1-23	Motor Frequency		All set-ups	FALSE	0	Uint16
1-24	Motor Current		All set-ups	FALSE	-2	Uint16
1-25	Motor Nominal Speed		All set-ups	FALSE	0	Uint16
1-29	Automatic Motor Tuning (AMT)	[0] Off	1 set-up	FALSE	-	Uint8
1-30	Stator Resistance (Rs)		All set-ups	FALSE	-2	Uint16
1-33	Stator Leakage Reactance (X1)		All set-ups	FALSE	-2	Uint32
1-35	Main Reactance (Xh)		All set-ups	FALSE	-2	Uint32
1-50	Motor Magnetisation at Zero Speed	100%	All set-ups	TRUE	0	Uint16
1-52	Min Speed Normal Magnetising [Hz]	0 Hz	All set-ups	TRUE	-1	Uint16
1-55	U/f Characteristic-U		All set-ups	TRUE	0	Uint16
1-56	U/f Characteristic-F		All set-ups	TRUE	0	Uint16
1-60	Low Speed Load Compensation	100%	All set-ups	TRUE	0	Uint16
1-61	High Speed Load Compensation	100%	All set-ups	TRUE	0	Uint16
1-62	Slip Compensation	100%	All set-ups	TRUE	0	Int16

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
1-63	Slip Compensation Time Constant	0.1 s	All set-ups	TRUE	-2	Uint16
1-71	Start Delay	0 s	All set-ups	TRUE	-1	Uint8
1-72	Start Function	[2] Coast/delay time	All set-ups	TRUE	-	Uint8
1-73	Flying Start	[0] Disabled	All set-ups	FALSE	-	Uint8
1-80	Function at Stop	[0] Coast	All set-ups	TRUE	-	Uint8
1-82	Min Speed for Function at Stop [Hz]	0 Hz	All set-ups	TRUE	-1	Uint16
1-90	Motor Thermal Protection	[0] No protection	All set-ups	TRUE	-	Uint8
1-93	Thermistor Resource	[0] None	All set-ups	FALSE	-	Uint8

5.2.7 2-** Brakes

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
2-00	DC Hold Current	50%	All set-ups	TRUE	0	Uint16
2-01	DC Brake Current	50%	All set-ups	TRUE	0	Uint16
2-02	DC Braking Time	10 s	All set-ups	TRUE	-1	Uint16
2-04	DC Brake Cut In Speed	0 Hz	All set-ups	TRUE	-1	Uint16
2-10	Brake Function	[0] Off	All set-ups	TRUE	-	Uint8
2-11	Brake Resistor (Ω)		All set-ups	TRUE	0	Uint16
2-14	Brake Voltage Reduce	0	All set-ups	FALSE	0	Uint8
2-16	AC Brake, Max current	100%	All set-ups	TRUE	0	Uint16
2-17	Over-voltage Control	[0] Disabled	All set-ups	TRUE	-	Uint8
2-20	Release Brake Current	0 A	All set-ups	TRUE	-2	Uint32
2-22	Activate Brake Speed [Hz]	0 Hz	All set-ups	TRUE	-1	Uint16

5.2.8 3-** Reference/Ramps

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
3-00	Reference Range	[0] Min to Max	All set-ups	TRUE	-	Uint8
3-02	Minimum Reference	0	All set-ups	TRUE	-3	Int32
3-03	Maximum Reference	50	All set-ups	TRUE	-3	Int32
3-10	Preset Reference	0%	All set-ups	TRUE	-2	Int16
3-11	Jog Speed [Hz]	5 Hz	All set-ups	TRUE	-1	Uint16
3-12	Catch up/slow Down Value	0%	All set-ups	TRUE	-2	Int16
3-14	Preset Relative Reference	0%	All set-ups	TRUE	-2	Int16
3-15	Reference Resource 1	[1] Analog in 53	All set-ups	TRUE	-	Uint8
3-16	Reference Resource 2	[2] Analog in 60	All set-ups	TRUE	-	Uint8
3-17	Reference Resource 3	[11] Local bus reference	All set-ups	TRUE	-	Uint8
3-18	Relative Scaling Reference Resource	[0] No function	All set-ups	TRUE	-	Uint8
3-40	Ramp 1 Type	[0] Linear	All set-ups	TRUE	-	Uint8
3-41	Ramp 1 Ramp up Time	3 s	All set-ups	TRUE	-2	Uint32
3-42	Ramp 1 Ramp Down Time	3 s	All set-ups	TRUE	-2	Uint32
3-50	Ramp 2 Type	[0] Linear	All set-ups	TRUE	-	Uint8
3-51	Ramp 2 Ramp up Time	3 s	All set-ups	TRUE	-2	Uint32
3-52	Ramp 2 Ramp down Time	3 s	All set-ups	TRUE	-2	Uint32

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
3-80	Jog Ramp Time	3 s	All set-ups	TRUE	-2	Uint32
3-81	Quick Stop Ramp Time	3 s	1 set-up	TRUE	-2	Uint32

5.2.9 4-** Limits/Warnings

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
4-10	Motor Speed Direction	[2] Both directions	All set-ups	FALSE	-	Uint8
4-12	Motor Speed Low Limit [Hz]	0 Hz	All set-ups	FALSE	-1	Uint16
4-14	Motor Speed High Limit [Hz]	65 Hz	All set-ups	FALSE	-1	Uint16
4-16	Torque Limit Motor Mode	150%	All set-ups	TRUE	0	Uint16
4-17	Torque Limit Generator Mode	100%	All set-ups	TRUE	0	Uint16
4-40	Warning Frequency Low	0Hz	All set-ups	TRUE	-1	Uint16
4-41	Warning Frequency High	400Hz	All set-ups	TRUE	-1	Uint16
4-50	Warning Current Low	0 A	All set-ups	TRUE	-2	Uint32
4-51	Warning Current High	26 A	All set-ups	TRUE	-2	Uint32
4-54	Warning Reference Low	-4999	All set-ups	TRUE	-3	Int32
4-55	Warning Reference High	4999	All set-ups	TRUE	-3	Int32
4-56	Warning Feedback Low	-4999	All set-ups	TRUE	-3	Int32
4-57	Warning Feedback High	4999	All set-ups	TRUE	-3	Int32
4-58	Missing Motor Phase Function	[1] On	All set-ups	FALSE	-	Uint8
4-61	Bypass Speed From [Hz]	0 Hz	All set-ups	TRUE	-1	Uint16
4-63	Bypass Speed To [Hz]	0 Hz	All set-ups	TRUE	-1	Uint16

5.2.10 5-** Digital In/Out

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
5-10	Terminal 18 Digital Input	[8] Start	All set-ups	TRUE	-	Uint8
5-11	Terminal 19 Digital Input	[10] Reversing	All set-ups	TRUE	-	Uint8
5-12	Terminal 27 Digital Input	[1] Reset	All set-ups	TRUE	-	Uint8
5-13	Terminal 29 Digital Input	[14] Jog	All set-ups	TRUE	-	Uint8
5-15	Terminal 33 Digital Input	[16] Preset ref bit 0	All set-ups	TRUE	-	Uint8
5-34	On Delay, Terminal 42 Digital Output	0.01s	All set-ups	TRUE	-2-	Uint16
5-35	Off Delay, Terminal 42 Digital Output	0.01s	All set-ups	TRUE	-2	Uint16
5-40	Function Relay	[0] No operation	All set-ups	TRUE	-	Uint8
5-41	On Delay, Relay	0.01s	All set-ups	TRUE	-2	Uint16
5-42	Off Delay, Relay	0.01s	All set-ups	TRUE	-2	Uint16
5-55	Terminal 33 Low Frequency	20 Hz	All set-ups	TRUE	0	Uint16
5-56	Terminal 33 High Frequency	5000 Hz	All set-ups	TRUE	0	Uint16
5-57	Terminal 33 Low Ref./Feedb. Value	0	All set-ups	TRUE	-3	Int32
5-58	Terminal 33 High Ref./Feedb. Value	50	All set-ups	TRUE	-3	Int32

5

5.2.11 6-** Analog In/Out

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
6-00	Live Zero Timeout Time	10 s	All set-ups	TRUE	0	Uint8
6-01	Live Zero TimeoutFunction	[0] Off	All set-ups	TRUE	-	Uint8
6-10	Terminal 53 Low Voltage	0.07 V	All set-ups	TRUE	-2	Uint16
6-11	Terminal 53 High Voltage	10 V	All set-ups	TRUE	-2	Uint16
6-12	Terminal 53 Low Current	0.14 mA	All set-ups	TRUE	-2	Uint16
6-13	Terminal 53 High Current	20 mA	All set-ups	TRUE	-2	Uint16
6-14	Terminal 53 Low Ref./Feedb. Value	0	All set-ups	TRUE	-3	Int32
6-15	Terminal 53 High Ref./Feedb. Value	50	All set-ups	TRUE	-3	Int32
6-16	Terminal 53 Filter Time Constant	0.01 s	All set-ups	TRUE	-2	Uint16
6-19	Terminal 53 mode	[0] Voltage mode	1 set-up	TRUE	-	Uint8
6-22	Terminal 60 Low Current	0.14 mA	All set-ups	TRUE	-2	Uint16
6-23	Terminal 60 High Current	20 mA	All set-ups	TRUE	-2	Uint16
6-24	Terminal 60 Low Ref./Feedb. Value	0	All set-ups	TRUE	-3	Int32
6-25	Terminal 60 High Ref./Feedb. Value	50	All set-ups	TRUE	-3	Int32
6-26	Terminal 60 Filter Time Constant	0.01 s	All set-ups	TRUE	-2	Uint16
6-80	LCP Potmeter Enable	1	1 set-up	FALSE	-	Uint8
6-81	LCP potentiometer Low Ref.	0	All set-ups	TRUE	-3	Int32
6-82	LCP potentiometer High Ref.	50	All set-ups	TRUE	-3	Int32
6-90	Terminal 42 Mode	[0] 0-20 mA	All set-ups	TRUE	-	Uint8
6-91	Terminal 42 Analog Output	[0] No operation	All set-ups	TRUE	-	Uint8
6-92	Terminal 42 Digital Output	[0] No operation	All set-ups	TRUE	-	Uint8
6-93	Terminal 42 Output Min Scale	0%	All set-ups	TRUE	-2	Uint16
6-94	Terminal 42 Output Max Scale	100%	All set-ups	TRUE	-2	Uint16

5.2.12 7-** Controllers

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
7-20	Process CL Feedback 1 Resource	[0] No function	All set-ups	TRUE	-	Uint8
7-30	Process PI Normal/ Inverse Control	[0] Normal	All set-ups	TRUE	-	Uint8
7-31	Process PI Anti Windup	[1] Enabled	All set-ups	TRUE	-	Uint8
7-32	Process PI Start Speed	0 Hz	All set-ups	TRUE	-1	Uint16
7-33	Process PI Proportional Gain	0.01	All set-ups	TRUE	-2	Uint16
7-34	Process PI Integral Time	9999 s	All set-ups	TRUE	-2	Uint32
7-38	Process PI Feed Forward Factor	0%	All set-ups	TRUE	0	Uint16
7-39	On Reference Bandwidth	5%	All set-ups	TRUE	0	Uint8

5.2.13 8-** Comm. and Options

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
8-01	Control Site	[0] Digital and ctrl.word	All set-ups	TRUE	-	Uint8
8-02	Control Word Source	[1] FC RS485	All set-ups	TRUE	-	Uint8
8-03	Control Word Timeout Time	1 s	1 set-up	TRUE	-1	Uint16
8-04	Control Word Timeout Function	[0] Off	1 set-up	TRUE	-	Uint8
8-06	Reset Control Word Timeout	[0] No function	1 set-up	TRUE	-	Uint8
8-30	Protocol	[0] FC	1 set-up	TRUE	0	Uint8
8-31	Address	1	1 set-up	TRUE	0	Uint8
8-32	FC Port Baud Rate	[2] 9600 Baud	1 set-up	TRUE	-	Uint8
8-33	FC Port Parity	[0] Even Parity 1 Stop Bit	1 set-up	TRUE	-	Uint8
8-35	Minimum Response Delay	0.01 s	1 set-up	TRUE	-3	Uint16
8-36	Max Response Delay	5 s	1 set-up	TRUE	-3	Uint16
8-43	FC Port PCD Read Configuration	0	1 set-up	TRUE	-	Uint8
8-50	Coasting Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-51	Quick Stop Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-52	DC Brake Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-53	Start Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-54	Reversing Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-55	Set-up Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-56	Preset Reference Select	[3] Logic OR	All set-ups	TRUE	-	Uint8
8-94	Bus feedback 1	0	All set-ups	TRUE	0	Int16

5.2.14 13-** Smart Logic

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
13-00	SL Controller Mode	[0] Off	1 set-up	TRUE	-	Uint8
13-01	Start Event	[39] Start command	1 set-up	TRUE	-	Uint8
13-02	Stop Event	[40] Drive stopped	1 set-up	TRUE	-	Uint8
13-03	Reset SLC	[0] Do not reset	1 set-up	TRUE	-	Uint8
13-10	Comparator Operand	[0] Disabled	1 set-up	TRUE	-	Uint8
13-11	Comparator Operator	[1] ApproxEqual	1 set-up	TRUE	-	Uint8
13-12	Comparator Value	0	1 set-up	TRUE	-1	Int32
13-20	SL Controller Timer	0 s	1 set-up	TRUE	-1	Uint32
13-40	Logic Rule Boolean 1	[0] False	1 set-up	TRUE	-	Uint8
13-41	Logic Rule Operator 1	[0] Disabled	1 set-up	TRUE	-	Uint8
13-42	Logic Rule Boolean 2	[0] False	1 set-up	TRUE	-	Uint8
13-43	Logic Rule Operator 2	[0] Disabled	1 set-up	TRUE	-	Uint8
13-44	Logic Rule Boolean 3	[0] False	1 set-up	TRUE	-	Uint8
13-51	SL Controller Event	[0] False	1 set-up	TRUE	-	Uint8
13-52	SL Controller Action	[0] Disabled	1 set-up	TRUE	-	Uint8

5.2.15 14-** Special Functions

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
14-01	Switching Frequency	[1] 4.0 kHz	All set-ups	TRUE	-	Uint8
14-03	Overmodulation	[1] On	All set-ups	FALSE	-	Uint8
14-12	Function at Mains Imbalance	[0] Trip	All set-ups	TRUE	-	Uint8
14-20	Reset Mode	[0] Manual reset	All set-ups	TRUE	-	Uint8

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
14-21	Automatic Restart Time	10 s	All set-ups	TRUE	0	Uint16
14-22	Operation Mode	[0] Normal operation	1 set-up	TRUE	-	Uint8
14-26	Action At Inverter Fault	[0] Trip	All set-ups	TRUE	-	Uint8
14-41	AEO Minimum Magnetisation	66 %	All set-ups	TRUE	0	Uint8
14-90	Fault Level	[3] Trip Lock	1 set-up	TRUE	-	Uint8

5.2.16 15-** Drive Information

Parameter number	Parameter description	Default value	2 Setup	Change During Operation	Conversion Index	Type
15-00	Operating Time	0	1 set-up	TRUE	0	Uint32
15-01	Running Hours	0	1 set-up	TRUE	0	Uint32
15-02	kWh Counter	0	1 set-up	TRUE	0	Uint32
15-03	Power Up's	0	1 set-up	TRUE	0	Uint32
15-04	Over Temp's	0	1 set-up	TRUE	0	Uint16
15-05	Over Volt's	0	1 set-up	TRUE	0	Uint16
15-06	Reset kWh Counter	[0] Do not reset	1 set-up	TRUE	-	Uint8
15-07	Reset Running Hours Counter	[0] Do not reset	1 set-up	TRUE	-	Uint8
15-30	Fault Log: Error Code	0	1 set-up	TRUE	0	Uint8
15-40	FC Type		1 set-up	FALSE	0	VisibleString
15-41	Power Section		1 set-up	FALSE	0	VisibleString
15-42	Voltage		1 set-up	FALSE	0	VisibleString
15-43	SW ID Control Card		1 set-up	FALSE	0	VisibleString
15-46	Frequency Converter Ordering No		1 set-up	FALSE	0	VisibleString
15-48	LCP Id No		1 set-up	FALSE	0	VisibleString
15-51	Frequency Converter Serial Number		1 set-up	FALSE	0	VisibleString

5.2.17 16-** Data Readouts

Parameter number	Parameter description	Default value	2 Setup	Change during operation	Conversion index	Type
16-00	Control Word	0	1 set-up	TRUE	0	Uint16
16-01	Reference [Unit]	0	1 set-up	TRUE	-3	Int32
16-02	Reference %	0	1 set-up	TRUE	-1	Int16
16-03	Status Word	0	1 set-up	TRUE	0	Uint16
16-05	Main Actual Value [%]	0	1 set-up	TRUE	-2	Int16
16-09	Custom Readout	0	1 set-up	TRUE	-2	Int32
16-10	Power [kW]	0	1 set-up	TRUE	-3	Uint16
16-11	Power [hp]	0	1 set-up	TRUE	-3	Uint16
16-12	Motor Voltage	0	1 set-up	TRUE	0	Uint16
16-13	Frequency	0	1 set-up	TRUE	-1	Uint16
16-14	Motor Current	0	1 set-up	TRUE	-2	Uint16
16-15	Frequency [%]	0	1 set-up	TRUE	-1	Uint16
16-18	Motor Thermal	0	1 set-up	TRUE	0	Uint8
16-30	DC Link Voltage	0	1 set-up	TRUE	0	Uint16
16-34	Heatsink Temp.	0	1 set-up	TRUE	0	Uint8
16-35	Inverter Thermal	0	1 set-up	TRUE	0	Uint8
16-36	Inv. Nom. Current	0	1 set-up	TRUE	-2	Uint16
16-37	Inv. Max. Current	0	1 set-up	TRUE	-2	Uint16
16-38	SL Controller State	0	1 set-up	TRUE	0	Uint8

Parameter number	Parameter description	Default value	2 Setup	Change during operation	Conversion index	Type
16-50	External Reference	0	1 set-up	TRUE	-1	Int16
16-51	Pulse Reference	0	1 set-up	TRUE	-1	Int16
16-52	Feedback [Unit]	0	1 set-up	TRUE	-3	Int32
16-60	Digital input 18,19,27,33	0	1 set-up	TRUE	0	Uint16
16-61	Digital input 29	0	1 set-up	TRUE	0	Uint8
16-62	Analog Input 53 (V)	0	1 set-up	TRUE	-2	Uint16
16-63	Analog Input 53 (mA)	0	1 set-up	TRUE	-2	Uint16
16-64	Analog Input 60	0	1 set-up	TRUE	-2	Uint16
16-65	Analog Output 42 [mA]	0	1 set-up	TRUE	-2	Uint16
16-68	Pulse input 33	20	1 set-up	TRUE	0	Uint16
16-71	Relay Output [bin]	0	1 set-up	TRUE	0	Uint8
16-72	Counter A	0	1 set-up	TRUE	0	Int16
16-73	Counter B	0	1 set-up	TRUE	0	Int16
16-86	FC Port REF 1	0	1 set-up	TRUE	0	Int16
16-90	Alarm Word	0	1 set-up	TRUE	0	Uint32
16-91	Alarm Word2	0	1 set-up	TRUE	0	UNIT32
16-92	Warning Word	0	1 set-up	TRUE	0	Uint32
16-94	Ext. Status Word	0	1 set-up	TRUE	0	Uint32

5.2.18 18-** Extended Motor Data

Parameter Number	Parameter Description	Default Value	2 Setup	Change During Operation	Conversion Index	Type
18-80	Stator Resistance (Rs in high resolution)	0.000	All set-ups	FALSE	-3	Uint32
16-01	(18-81) Stator Leakage Reactance (X1 in high resolution)	0.000	All set-ups	FALSE	-3	Uint32

6 Troubleshooting

6.1 Warnings and Alarms

A warning or an alarm is signalled by the relevant LED on the front of the frequency converter and indicated by a code on the display.

A warning remains active until its cause is no longer present. Under certain circumstances operation of the motor may still be continued. Warning messages may be critical, but are not necessarily so.

In the event of an alarm, the frequency converter will have tripped. Alarms must be reset to restart operation once their cause has been rectified.

This may be done in 4 ways:

1. By pressing [Reset].
2. Via a digital input with the "Reset" function.
3. Via serial communication.

NOTICE

After a manual reset press [Reset], [Auto On] or [Hand On] to restart the motor.

If an alarm cannot be reset, the reason may be that its cause has not been rectified, or the alarm is trip-locked (see also *Table 6.1*).

Alarms that are trip-locked offer additional protection, means that the mains supply must be switched off before the alarm can be reset. After being switched back on, the frequency converter is no longer blocked and may be reset as described above once the cause has been rectified. Alarms that are not trip-locked can also be reset using the automatic reset function in *14-20 Reset Mode* (Warning: automatic wake-up is possible!)
If a warning and alarm is marked against a code in the *Table 6.1*, this means that either a warning occurs before an alarm, or it can be specified whether it is a warning or an alarm that is to be displayed for a given fault.
This is possible, for instance, in *1-90 Motor Thermal Protection*. After an alarm or trip, the motor carries on coasting, and the alarm and warning flash on the frequency converter. Once the problem has been rectified, only the alarm continues flashing.

No.	Description	Warning	Alarm	Trip Lock	Error	Parameter Reference
2	Live zero error	(X)	(X)			6-01
4	Mains phase loss	(X)	(X)	(X)		14-12
7	DC over voltage	X	X			
8	DC under voltage	X	X			
9	Inverter overloaded	X	X			
10	Motor ETR over temperature	(X)	(X)			1-90
11	Motor thermistor over temperature	(X)	(X)			1-90
12	Torque limit	(X)				4-16, 4-17
13	Over Current	X	X	X		
14	Earth fault	X	X	X		
16	Short Circuit		X	X		
17	Control word timeout	(X)	(X)			8-04
25	Brake resistor short-circuited		X	X		
27	Brake chopper short-circuited		X	X		
28	Brake Check		X			
29	Power board over temp	X	X	X		
30	Motor phase U missing		(X)	(X)		4-58
31	Motor phase V missing		(X)	(X)		4-58
32	Motor phase W missing		(X)	(X)		4-58
38	Internal fault		X	X		
44	Earth fault 2		X	X		
47	Control Voltage Fault		X	X		
51	AMT check U_{nom} and I_{nom}		X			
52	AMT low I_{nom}		X			
53	AMT motor too big		X			

No.	Description	Warning	Alarm	Trip Lock	Error	Parameter Reference
54	AMT motor too small		X			
55	AMT Parameter out of range		X			
59	Current limit	X				
63	Mechanical Brake Low		X			
80	Drive Initialized to Default Value		X			
84	The connection between drive and LCP is lost				X	
85	Button disabled				X	
86	Copy fail				X	
87	LCP data invalid				X	
88	LCP data not compatible				X	
89	Parameter read only				X	
90	Parameter database busy				X	
91	Parameter value is not valid in this mode				X	
92	Parameter value exceeds the min/max limits				X	

Table 6.1 Alarm/Warning Code List

(X) Dependent on parameter

A trip is the action when an alarm has appeared. The trip will coast the motor and can be reset by pressing [Reset] or make a reset by a digital input (parameter group 5-1* [1]). The original event that caused an alarm cannot damage the frequency converter or cause dangerous conditions. A trip lock is an action when an alarm occurs, which may cause damage to frequency converter or connected parts. A trip lock situation can only be reset by a power cycling.

Warning	yellow
Alarm	flashing red

Table 6.2 LED Indication

The alarm words, warning words and extended status words can be read out via serial bus or optional fieldbus for diagnosis. See also *16-90 Alarm Word*, *16-92 Warning Word* and *16-94 Ext. Status Word*.

			Par. 16-90	Par. 16-91	Par. 16-92	Par. 16-94
Bit	Hex	Dec	AlarmWord	AlarmWord2	WarningWord	ExtendedStatusWord
0	1	1	Brake check	Control Voltage Fault		Ramping
1	2	2	Pwr.card temp		Pwr.card temp	AMT running
2	4	4	Earth Fault			Start CW/CCW
3	8	8				Slow down
4	10	16	Ctrl.word TO		Ctrl.word TO	Catch up
5	20	32	Over Current		Over Current	Above Feedback High
6	40	64			Torque limit	Below Feedback Low
7	80	128	Motor th over		Motor th over	Output current high
8	100	256	Motor ETR over		Motor ETR over	Output current low
9	200	512	Inverter overload		Inverter overload	Above Frequency High
10	400	1024	DC under volt		DC under volt	Below Frequency Low
11	800	2048	DC over volt		DC over volt	
12	1000	4096	Short Circuit			
13	2000	8192				Braking
14	4000	16384	Mains ph. loss		Mains ph. loss	
15	8000	32768	AMT Not OK			OVC active
16	10000	65536	Live zero error		Live zero error	AC brake
17	20000	131072	Internal fault			
18	40000	262144				
19	80000	524288	U phase loss			Above Reference High
20	100000	1048576	V phase loss			Below Reference Low
21	200000	2097152	W phase loss			Local Ref./Remote Ref.
22	400000	4194304				
23	800000	8388608				Protection Mode
24	1000000	16777216				
25	2000000	33554432			Current limit	
26	4000000	67108864	Brake resistor short-circuit			
27	8000000	134217728	Brake IGBT short-circuit			
28	10000000	268435456	M4/M5: Earth Fault (Desat)		MotorPhaseMissing	
29	20000000	536870912	Drive initialised			
30	40000000	1073741824				
31	80000000	2147483648	Mech. brake low			DatabaseBusy

Table 6.3 Alarm, Warning, and Extended Status Word

The alarm words, warning words and extended staus words can be read out via serial bus for diagnose. See also *16-94 Ext. Status Word*.

WARNING/ALARM 2, Live zero error
Signal on terminal 53 or 60 is less than 50% of value set in *6-10 Terminal 53 Low Voltage*, *6-12 Terminal 53 Low Current* and *6-22 Terminal 60 Low Current*.

WARNING/ALARM 4, Mains phase loss
A phase is missing on the supply side, or the mains voltage imbalance is too high. This message also appears for a fault in the input rectifier on the frequency converter.

Troubleshooting
Check the supply voltage and supply currents to the frequency converter. The fault may be caused by mains distortions. Installing Danfoss line filter may rectify this problem.

WARNING/ALARM 7, DC overvoltage
If the intermediate circuit voltage exceeds the limit, the frequency converter trips after a time.

Troubleshooting

Connect a brake resistor

Extend the ramp time

Change the ramp type

Activate the functions in *2-10 Brake Function*

Increase *14-26 Trip Delay at Inverter Fault*

The fault may be caused by mains distortions. Installing Danfoss Line Filter may rectify this problem.

WARNING/ALARM 8, DC under voltage
If the DC link voltage drops below the undervoltage limit, the frequency converter checks if a 24 V DC back-up supply is connected. If no 24 V DC back-up supply is connected, the frequency converter trips after a fixed time delay. The time delay varies with unit size.

Troubleshooting

- Check that the supply voltage matches the frequency converter voltage.
- Perform an input voltage test.
- Perform a soft charge circuit test.

WARNING/ALARM 9, Inverter overload
The frequency converter has run with more than 100% overload for too long and is about to cut out. The counter for electronic thermal inverter protection issues a warning at 98% and trips at 100%, while giving an alarm. The frequency converter cannot be reset until the counter is below 90%.

Troubleshooting

- Compare the output current shown on the LCP with the frequency converter rated current.
- Compare the output current shown on the LCP with the measured motor current.
- Display the thermal drive load on the LCP and monitor the value. When running above the frequency converter continuous current rating, the counter increases. When running below the frequency converter continuous current rating, the counter decreases.

WARNING/ALARM 10, Motor overload temperature
According to the electronic thermal protection (ETR), the motor is too hot. Select whether the frequency converter gives a warning or an alarm when the counter reaches 100% in *1-90 Motor Thermal Protection*. The fault occurs when the motor is overloaded by more than 100% for too long.

Troubleshooting

Check for motor overheating.

Check if the motor is mechanically overloaded

Check that the motor current set in *1-24 Motor Current* is correct.

Ensure that motor data in parameters 1-20 through 1-25 are set correctly.

Running AMT in 1-29 Automatic Motor Tuning (AMT). The inverter peak current limit (approx. 200% of the rated current) is exceeded. The warning will last approx. 8-12 s, then the frequency converter trips and issues an alarm. Turn off the frequency converter and check if the motor shaft can be turned and if the motor size matches the frequency converter. If extended mechanical brake control is selected, trip can be reset externally. may tune the frequency converter to the motor more accurately and reduce thermal loading.

WARNING/ALARM 11, Motor thermistor overtemp
The thermistor might be disconnected. Select whether the frequency converter gives a warning or an alarm in *1-90 Motor Thermal Protection*.

Troubleshooting

Check for motor overheating.

Check if the motor is mechanically overloaded.

WARNING/ALARM 13, Over current
The inverter peak current limit (approx. 200% of the rated current) is exceeded. The warning will last approx. 8-12 s, then the frequency converter trips and issues an alarm. Turn off the frequency converter and check if the motor shaft can be turned and if the motor size matches the frequency converter. If extended mechanical brake control is selected, trip can be reset externally.

Troubleshooting

Remove power and check if the motor shaft can be turned.

Check that the motor size matches the frequency converter.

Check parameters 1-20 through 1-25. for correct motor data.

ALARM 14, Earth (ground) fault
There is current from the output phase to ground, either in the cable between the frequency converter and the motor or in the motor itself.

Troubleshooting

- Remove power to the frequency converter and repair the ground fault.
- Check for ground faults in the motor by measuring the resistance to ground of the motor cables and the motor with a megohmmeter.

ALARM 16, Short circuit
There is short-circuiting in the motor or motor wiring.

Troubleshooting

- Remove the power to the frequency converter and repair the short circuit.

WARNING/ALARM 17, Control word timeout
There is no communication to the frequency converter. The warning is only active when *8-04 Control Word Timeout Function* is NOT set to *[0] Off*.
If *8-04 Control Word Timeout Function* is set to *[5] Stop and Trip*, a warning appears and the frequency converter ramps down until it trips, while giving an alarm. *8-03 Control Timeout Time* could possibly be increased.

Troubleshooting

- Check connections on the serial communication cable.
- Increase *8-03 Control Word Timeout Time*.
- Check the operation of the communication equipment.
- Verify a proper installation based on EMC requirements.

ALARM 25, Brake resistor short circuit
The brake resistor is monitored during operation. If a short circuit occurs, the brake function is disabled and the warning appears. The frequency converter is still operational but without the brake function. Remove power from the frequency converter and replace the brake resistor (see *2-15 Brake Check*).

ALARM 27, Brake chopper fault
The brake transistor is monitored during operation, and if a short circuit occurs, the brake function is disabled and a warning is issued. The frequency converter is still operational but, since the brake transistor has short-circuited, substantial power is transmitted to the brake resistor, even if it is inactive.

Troubleshooting

- Remove power to the frequency converter and remove the brake resistor.

ALARM 28, Brake check failed
The brake resistor is not connected or not working.

ALARM 29, Heat Sink temp
The maximum temperature of the heat sink has been exceeded. The temperature fault does not reset until the temperature drops below a defined heat sink temperature. The trip and reset points are different based on the frequency converter power size.

Troubleshooting
Check for the following conditions:

- Ambient temperature too high.
- Motor cables too long.
- Incorrect airflow clearance above and below the frequency converter.
- Blocked airflow around the frequency converter.
- Damaged heat sink fan.
- Dirty heat sink.

ALARM 30, Motor phase U missing
Motor phase U between the frequency converter and the motor is missing.

Troubleshooting

- Remove the power from the frequency converter and check motor phase U.

ALARM 31, Motor phase V missing
Motor phase V between the frequency converter and the motor is missing.

Troubleshooting

- Remove the power from the frequency converter and check motor phase V.

ALARM 32, Motor phase W missing
Motor phase W between the frequency converter and the motor is missing.

Troubleshooting

- Remove the power from the frequency converter and check motor phase W.

ALARM 38, Internal fault

Troubleshooting

- Cycle power.
- Check that the option is properly installed.
- Check for loose or missing wiring.

It may be necessary to contact the local Danfoss supplier or service department. Note the code number for further troubleshooting directions.

ALARM 46, Gate drive voltage fault
The supply on the power card is out of range.

There are 3 power supplies generated by the switch mode power supply (SMPS) on the power card: 24 V, 5 V, and ±18 V.

Troubleshooting

- Check for a defective power card.

ALARM 51, AMT check U_{nom} and I_{nom}
The settings for motor voltage, motor current, and motor power are wrong. Check the settings in parameters 1-20 to 1-25.

ALARM 55, AMA parameter out of range
The parameter values of the motor are outside of the acceptable range. AMA does not run.

ALARM 63, Mechanical brake low
The actual motor current has not exceeded the release brake current within the start delay time window.

ALARM 80, Drive initialised to default value
Parameter settings are initialised to default settings after a manual reset. To clear the alarm, reset the unit.

ERROR 84,The connection between drive and LCP is lost
Try to reassemble the LCP gently.

ERROR 85, Button disabled
See parameter group *0-4* LCP*

ERROR 86, Copy fail
An error occurred while copying from frequency converter to LCP or vice versa.

ERROR 87, LCP data invalid
Occurs when copying from LCP if the LCP contains erroneous data - or if no data was uploaded to the LCP.

ERROR 88,LCP data not compatible
Occurs when copying from LCP if data are moved between frequency converters with major differences in software versions.

ERROR 89, Parameter read only
Occurs when trying to write to a read-only parameter.

ERROR 90, Parameter database busy
LCP and RS-485 connection are trying to update parameters simultaneously.

ERROR 91, Parameter value is not valid in this mode
Occurs when trying to write an illegal value to a parameter.

ERROR 92, Parameter value exceeds the min/max limits
Occurs when trying to set a value outside the range. Parameter can only be changed when the motor is stopped. Err. A wrong password was entered, occurs when using a wrong password for changing a password-protected parameter.

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